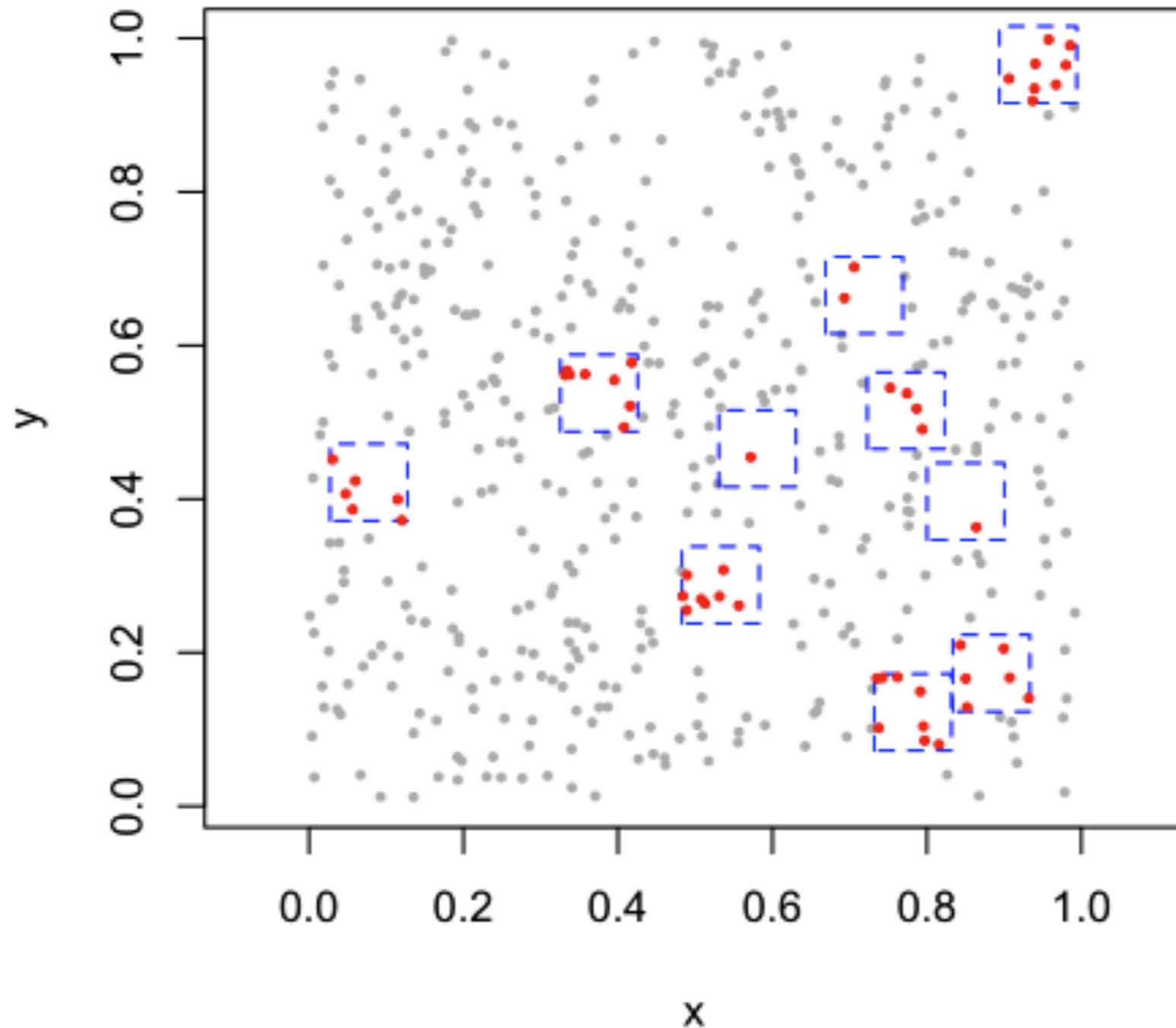


# Week 9: Distance Sampling

WLF 504: Applied Population Analysis  
Fall 2017

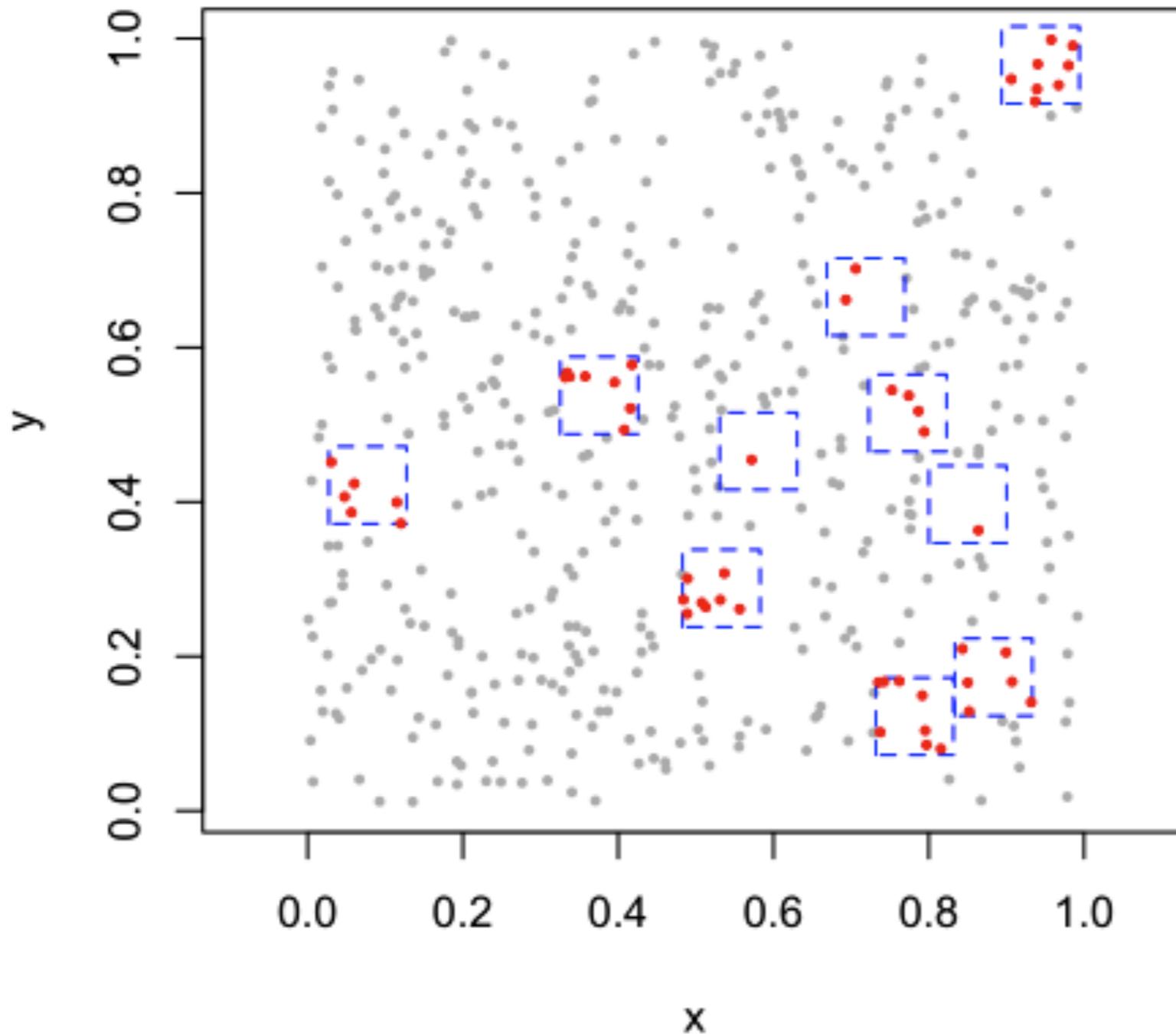
# Why distance sampling?

Could count animals in random quadrats...



# Why distance sampling?

Density/abundance easy to estimate...

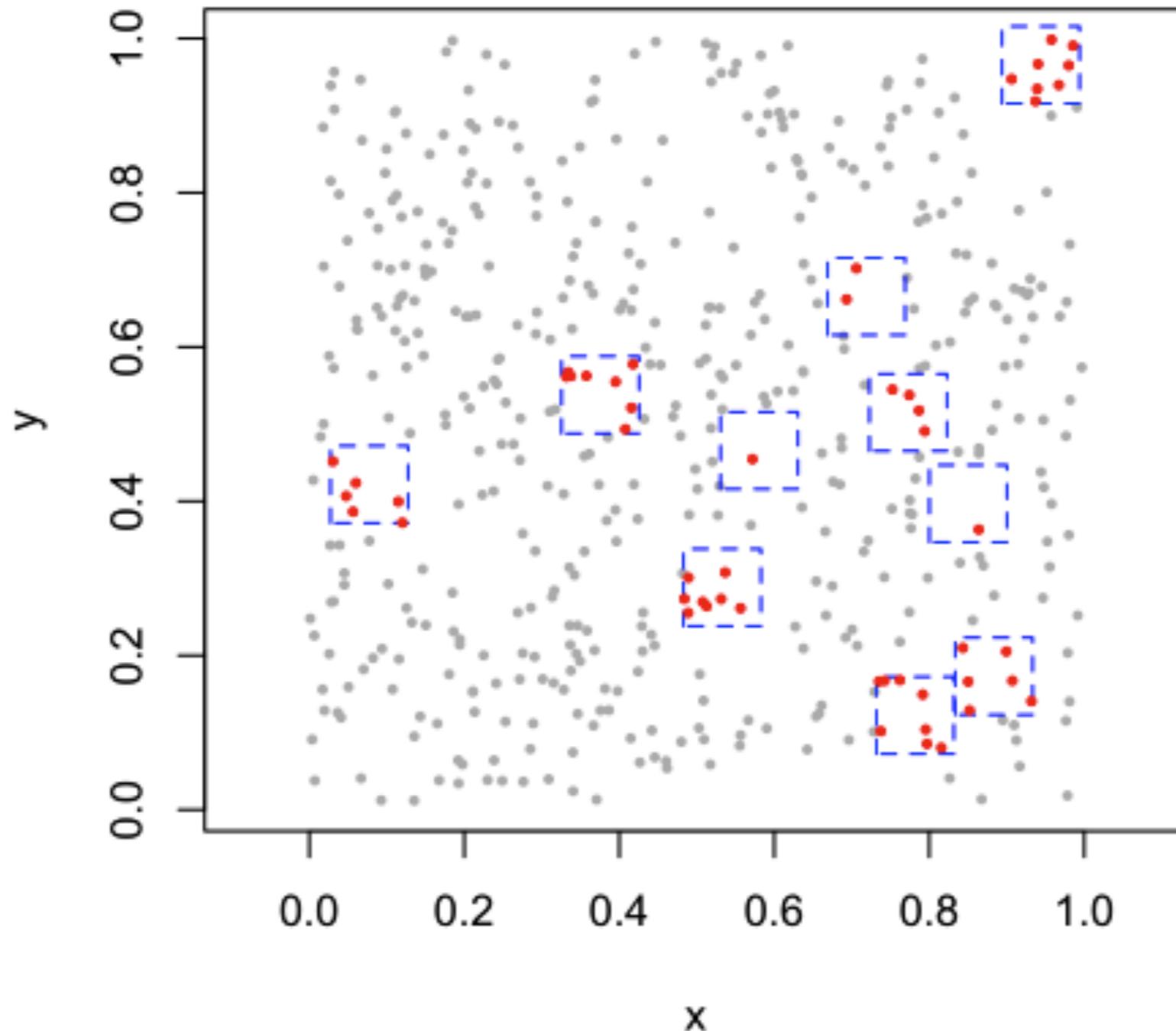


$$D = N/A$$

**Density =  
Number of  
animals/area**

# Why distance sampling?

Density/abundance easy to estimate if we count ALL critters in the quadrats...

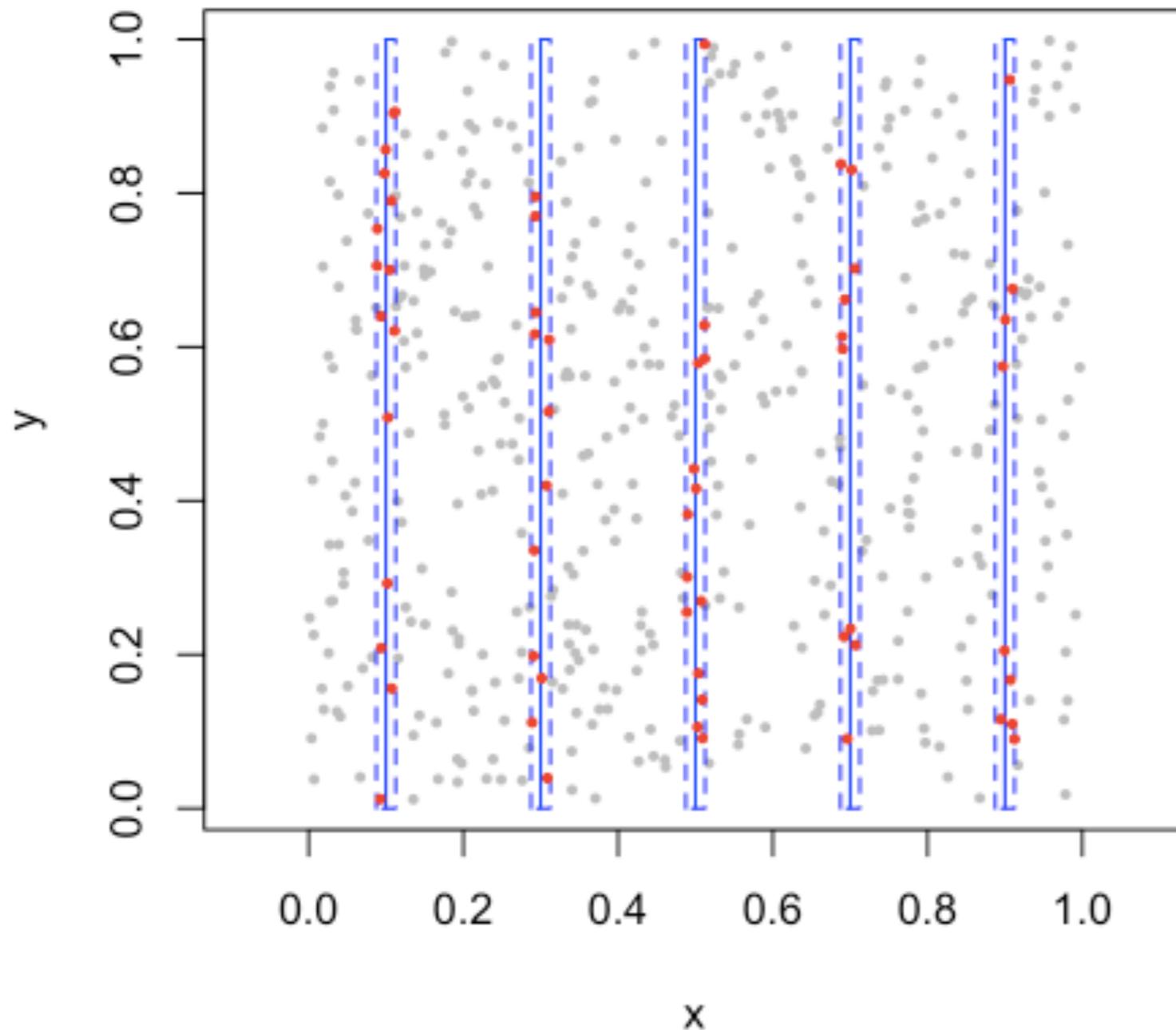


$$\hat{D} = n/a$$

**Density est. =  
number  
counted/  
covered area**

But much more convenient to walk transects...

Density/abundance calc. the same if we see ALL critters within the transect strip...

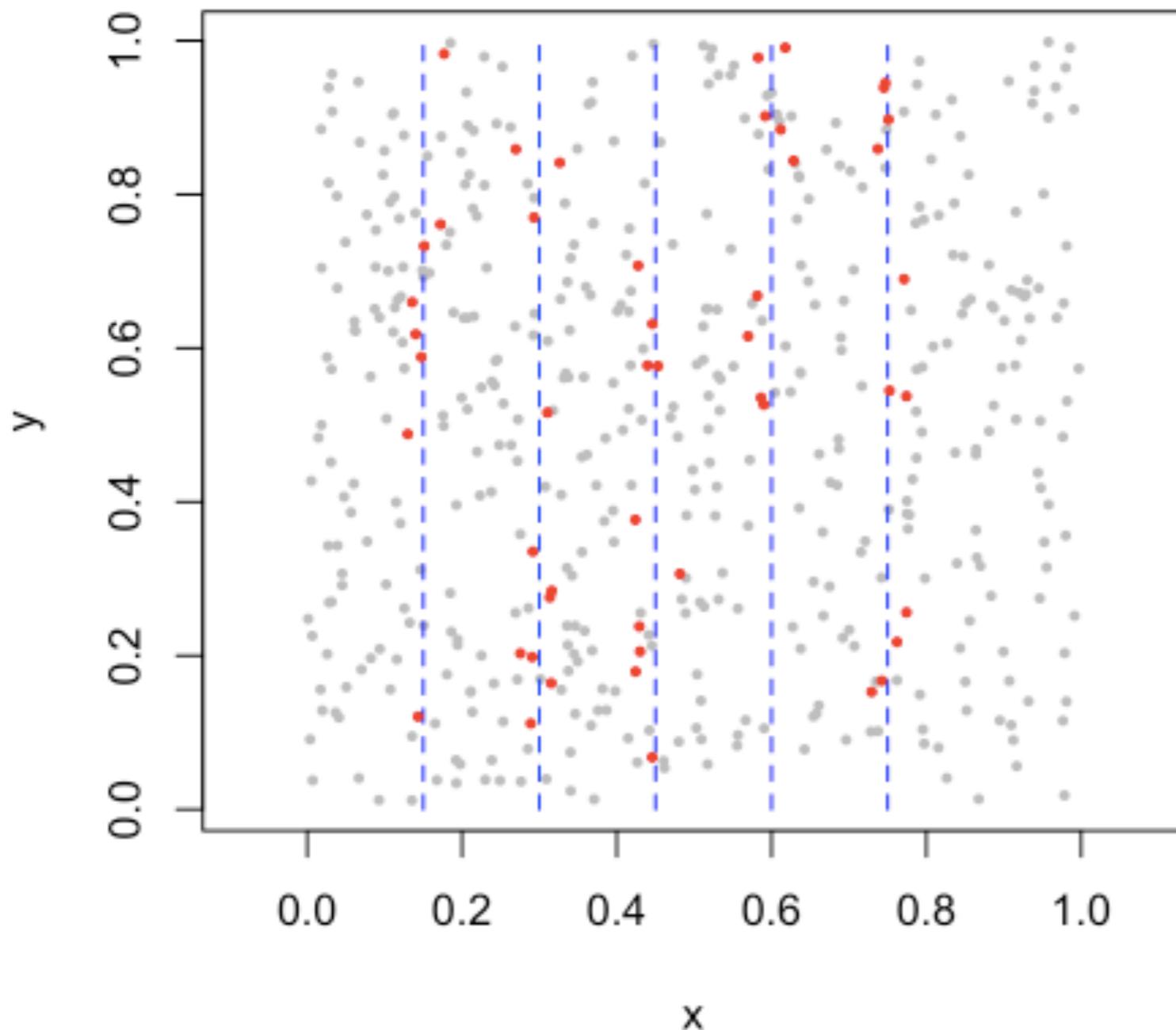


$$\hat{D} = n/a$$

**Density est. =  
number  
counted/  
covered area**

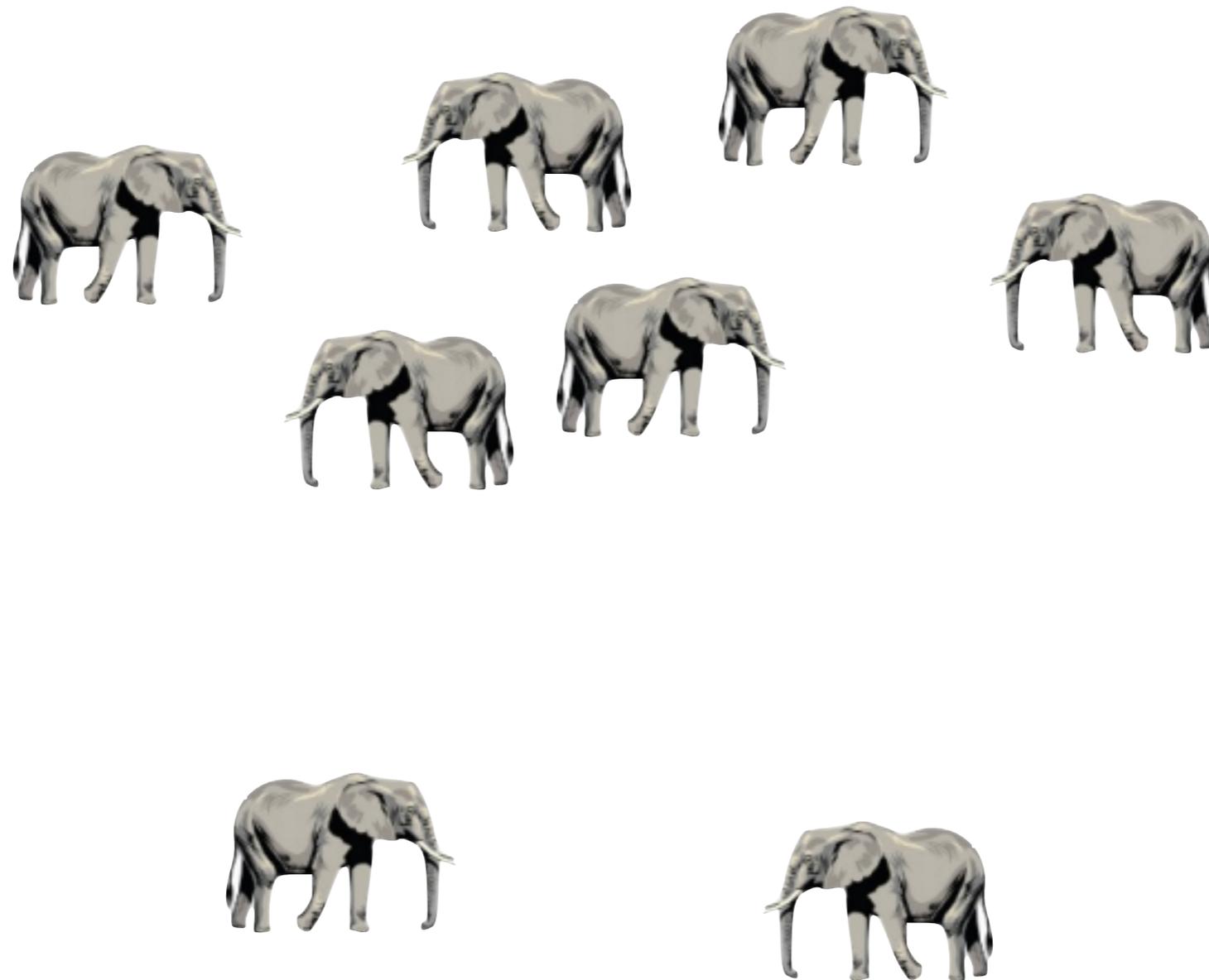
# But...

We definitely don't see all the animals along a transect within a certain strip

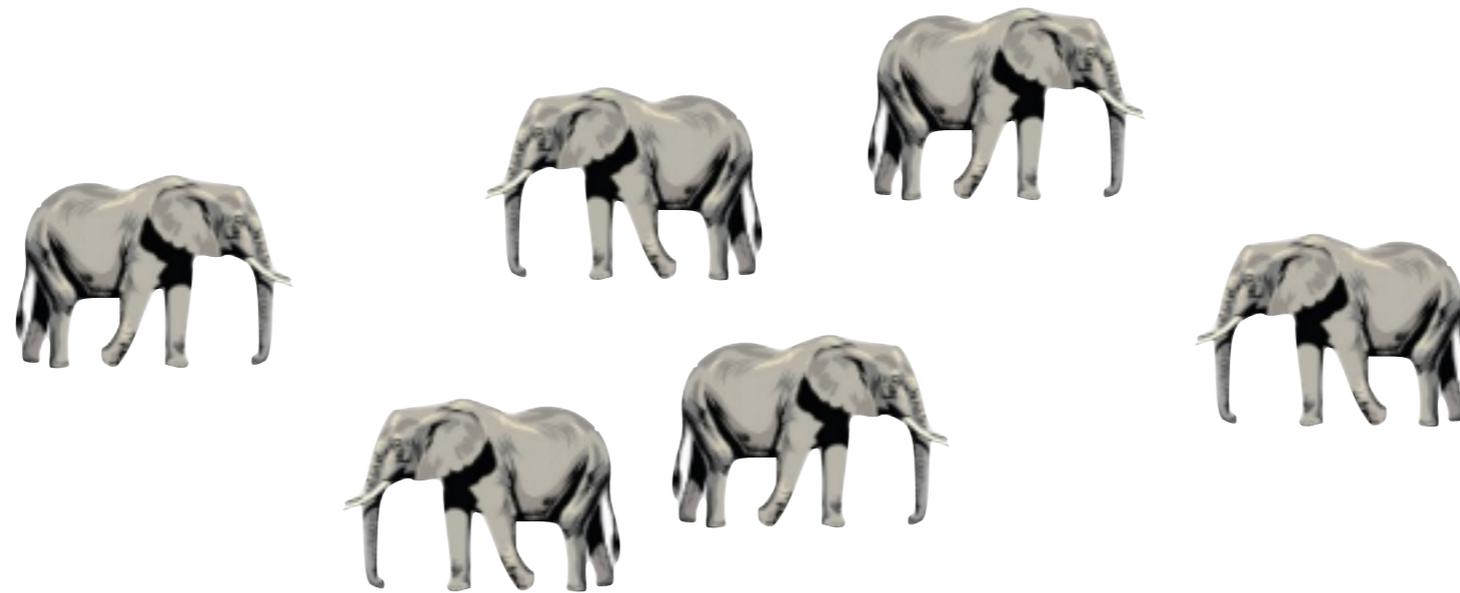


—> imperfect detection (P), dependend on **distance** from transect

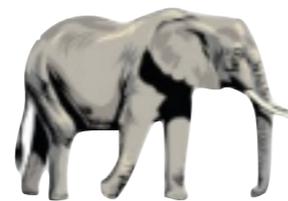
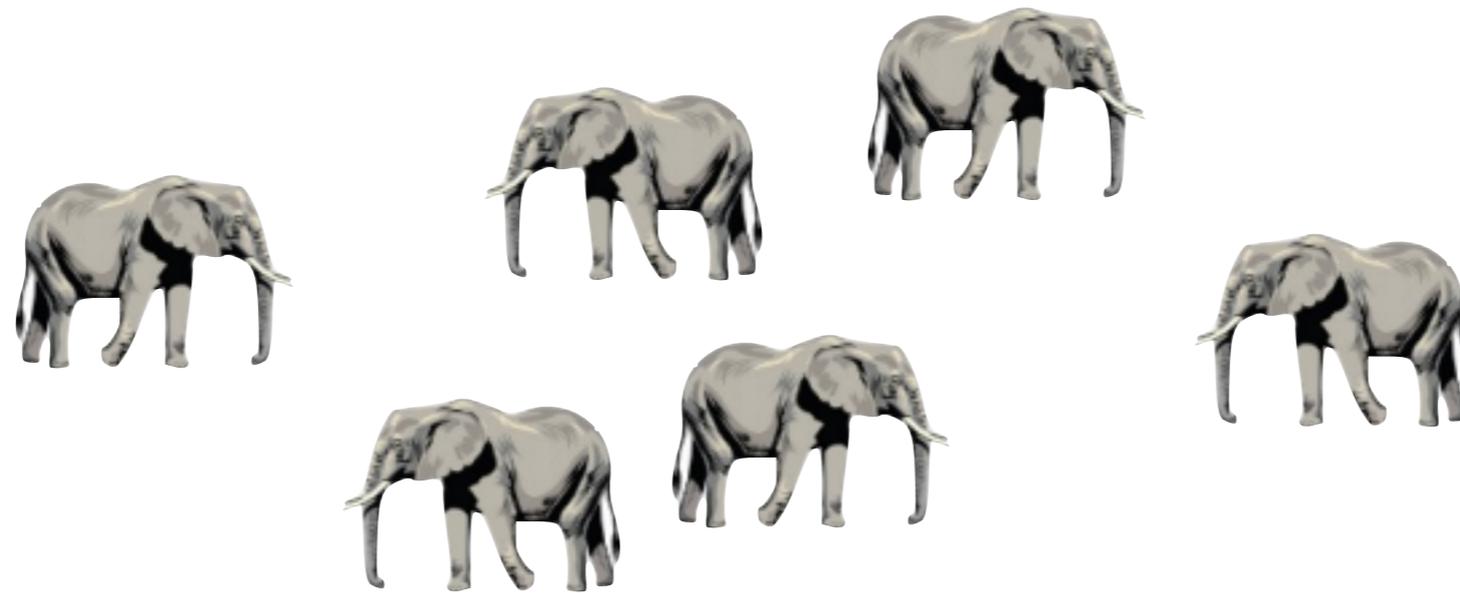
# What is distance sampling?



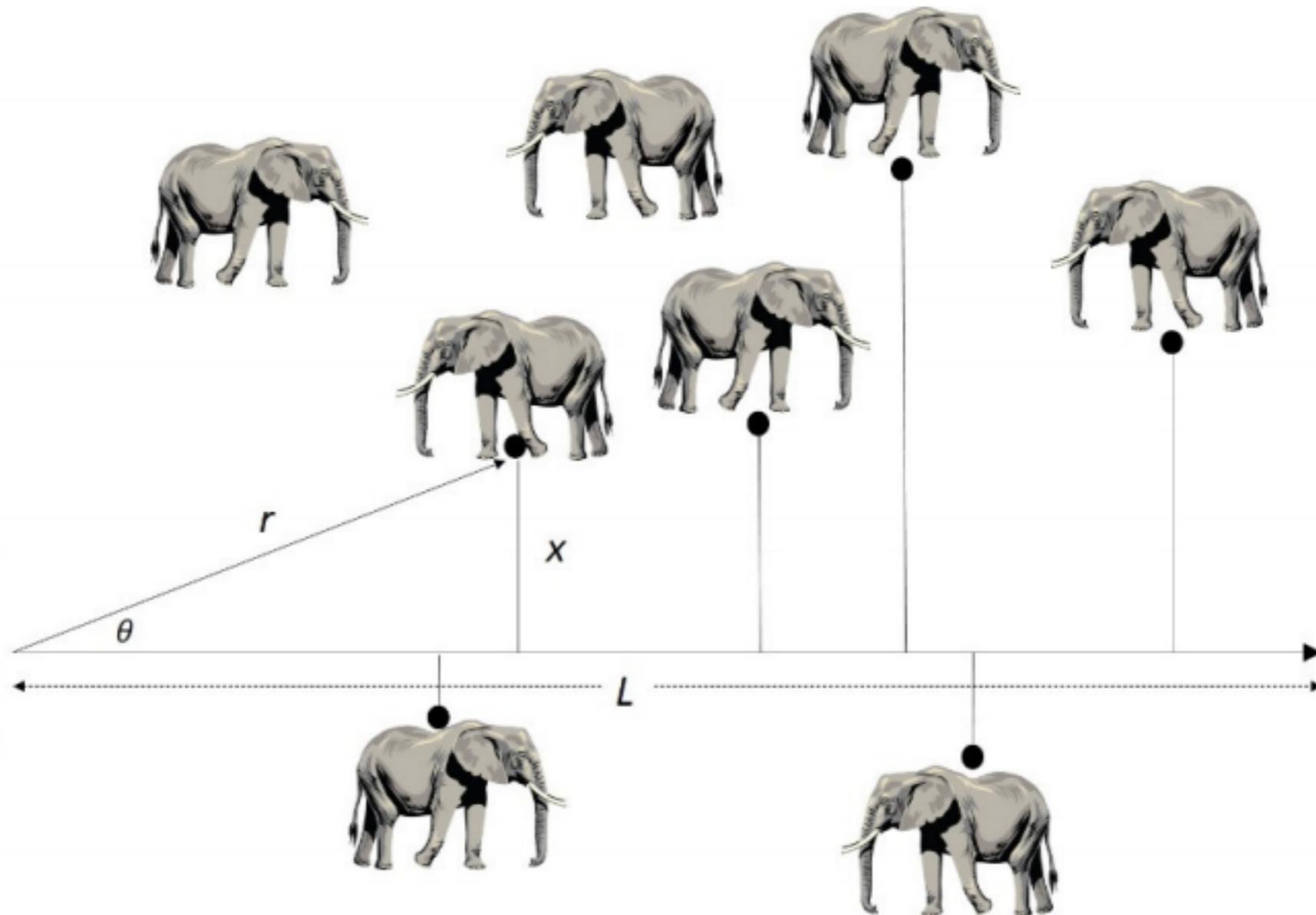
# What is distance sampling?



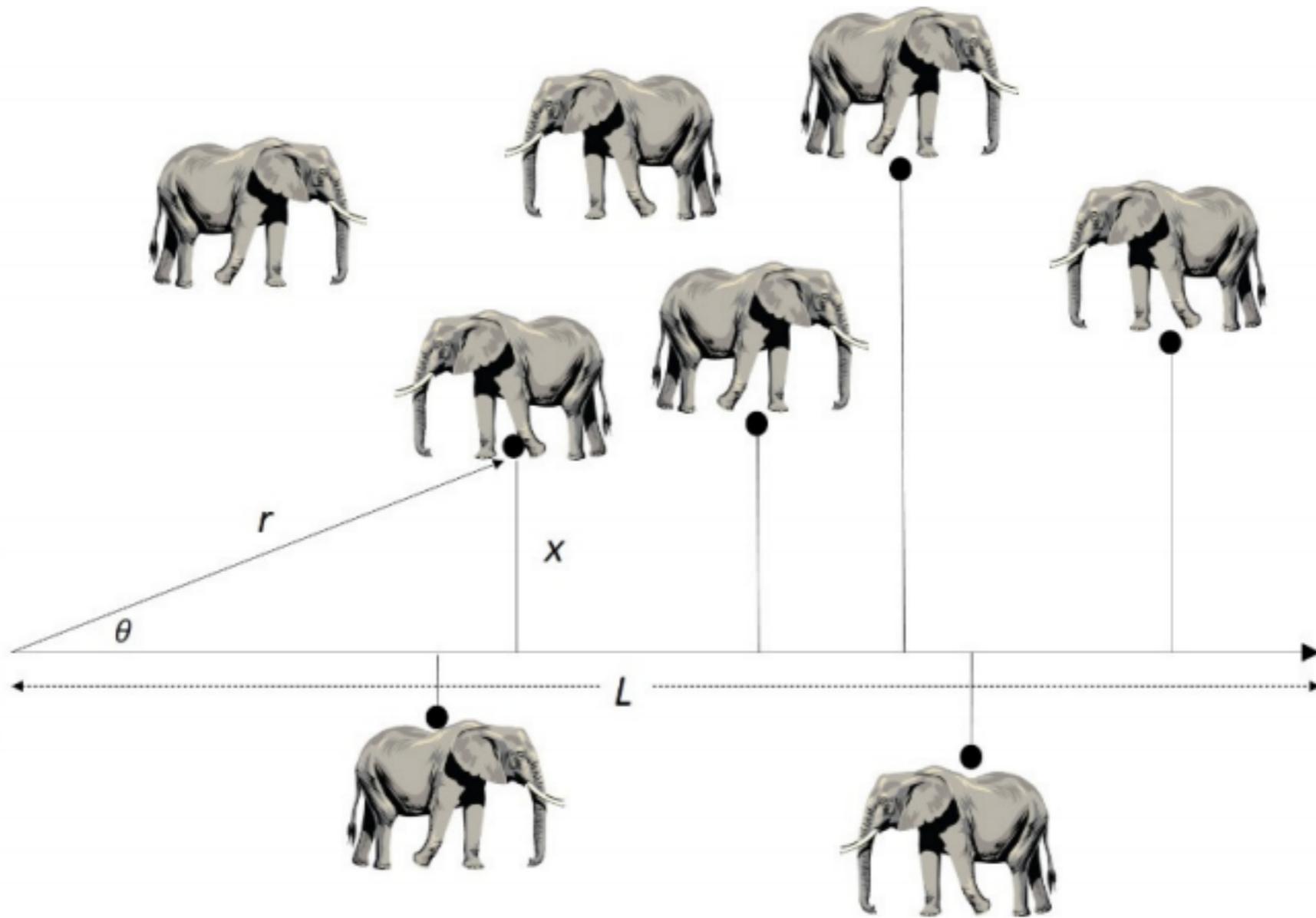
# What is distance sampling?



Animal doesn't need to be perpendicular to observer...

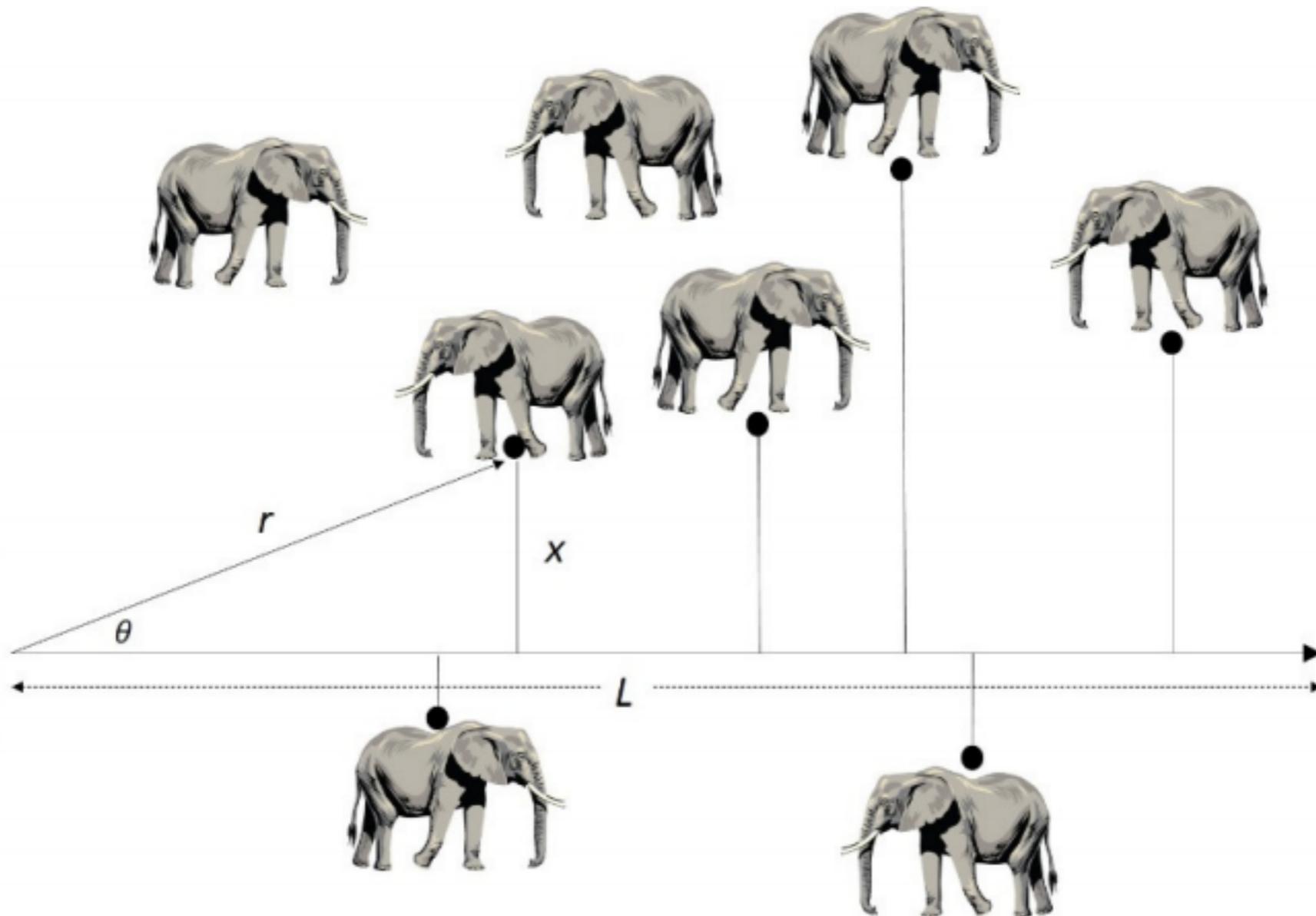


Want to solve for  $x$ ...

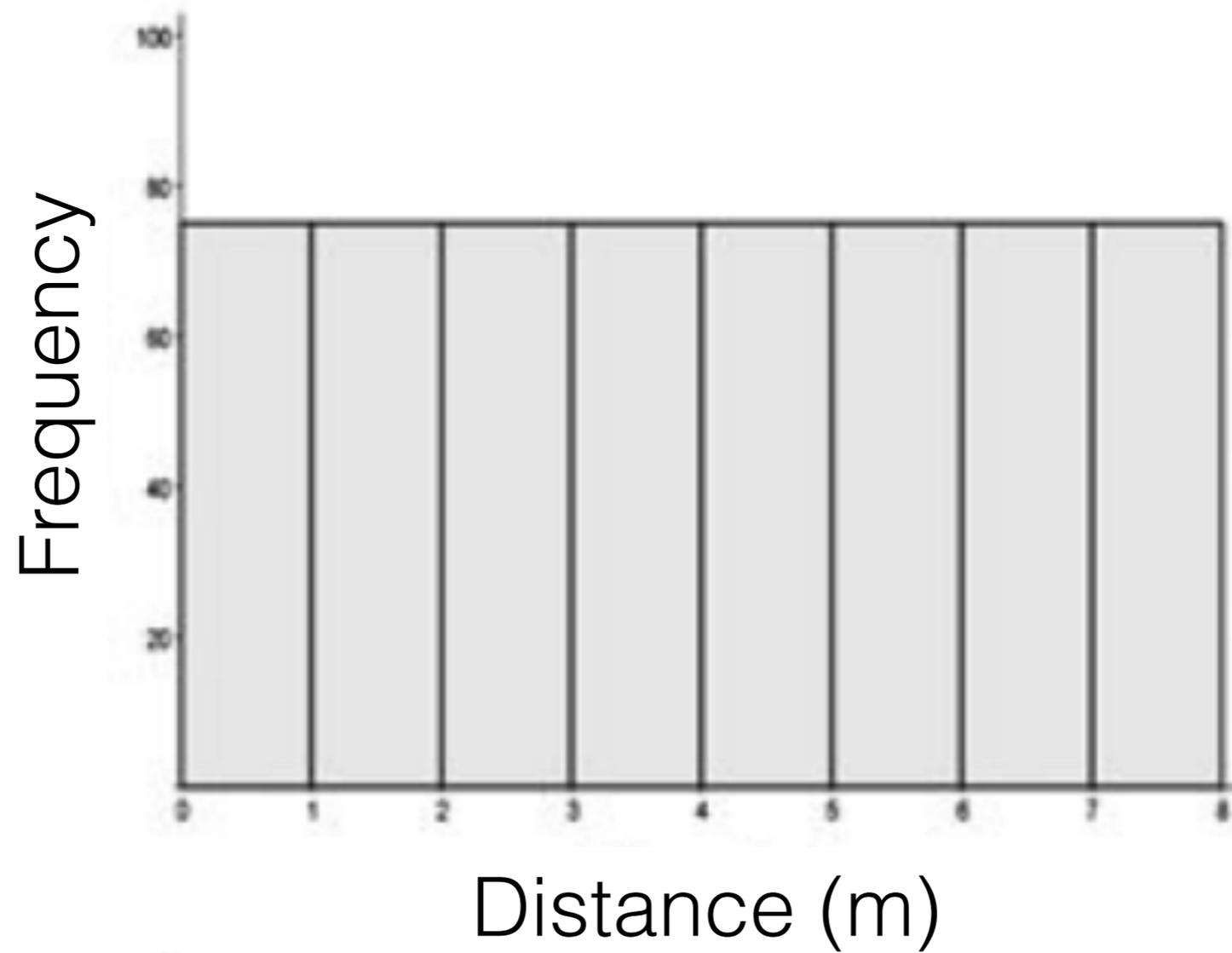


$$\sin(\theta) = r/x$$

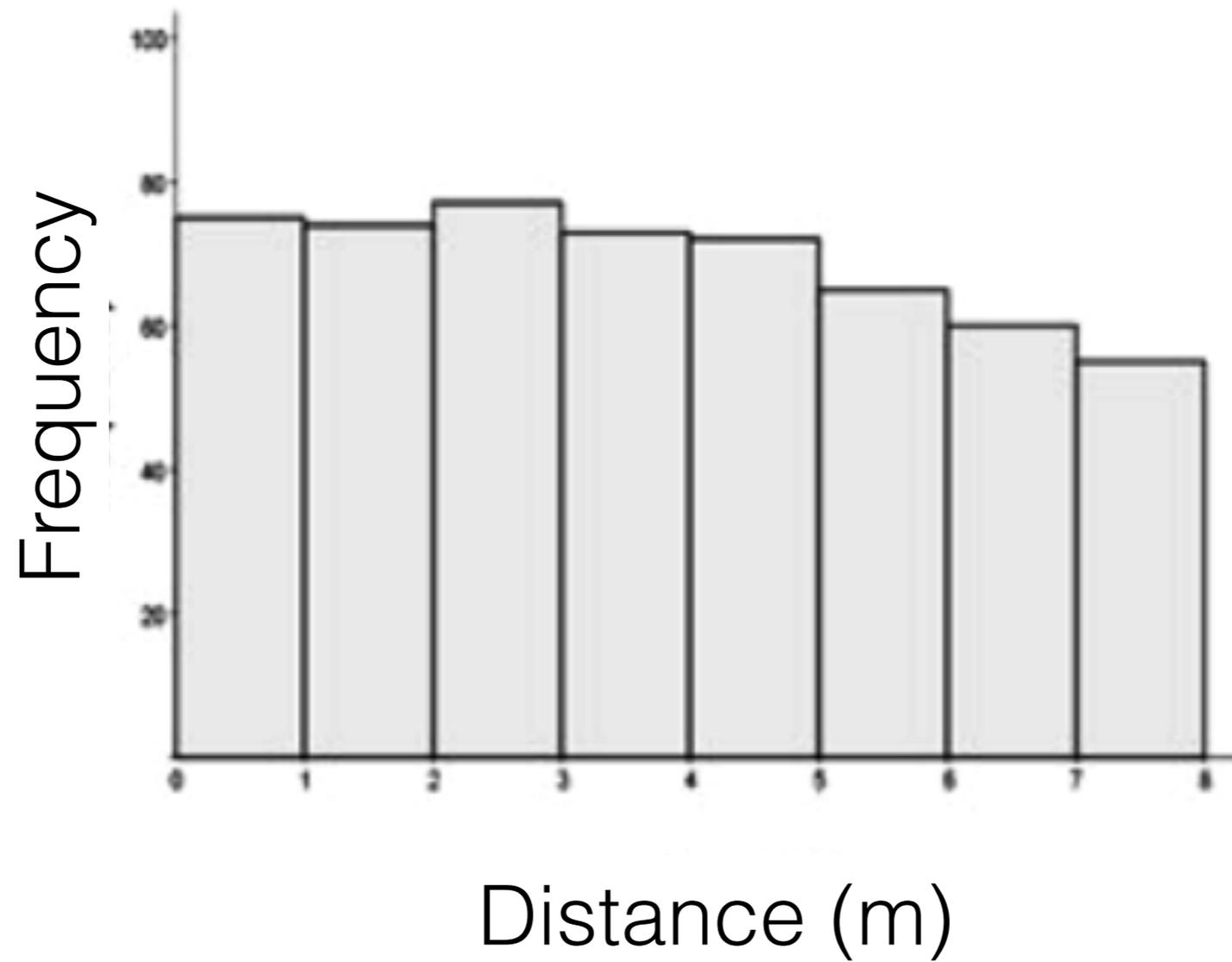
$$\mathbf{x = \sin(\theta)/r}$$



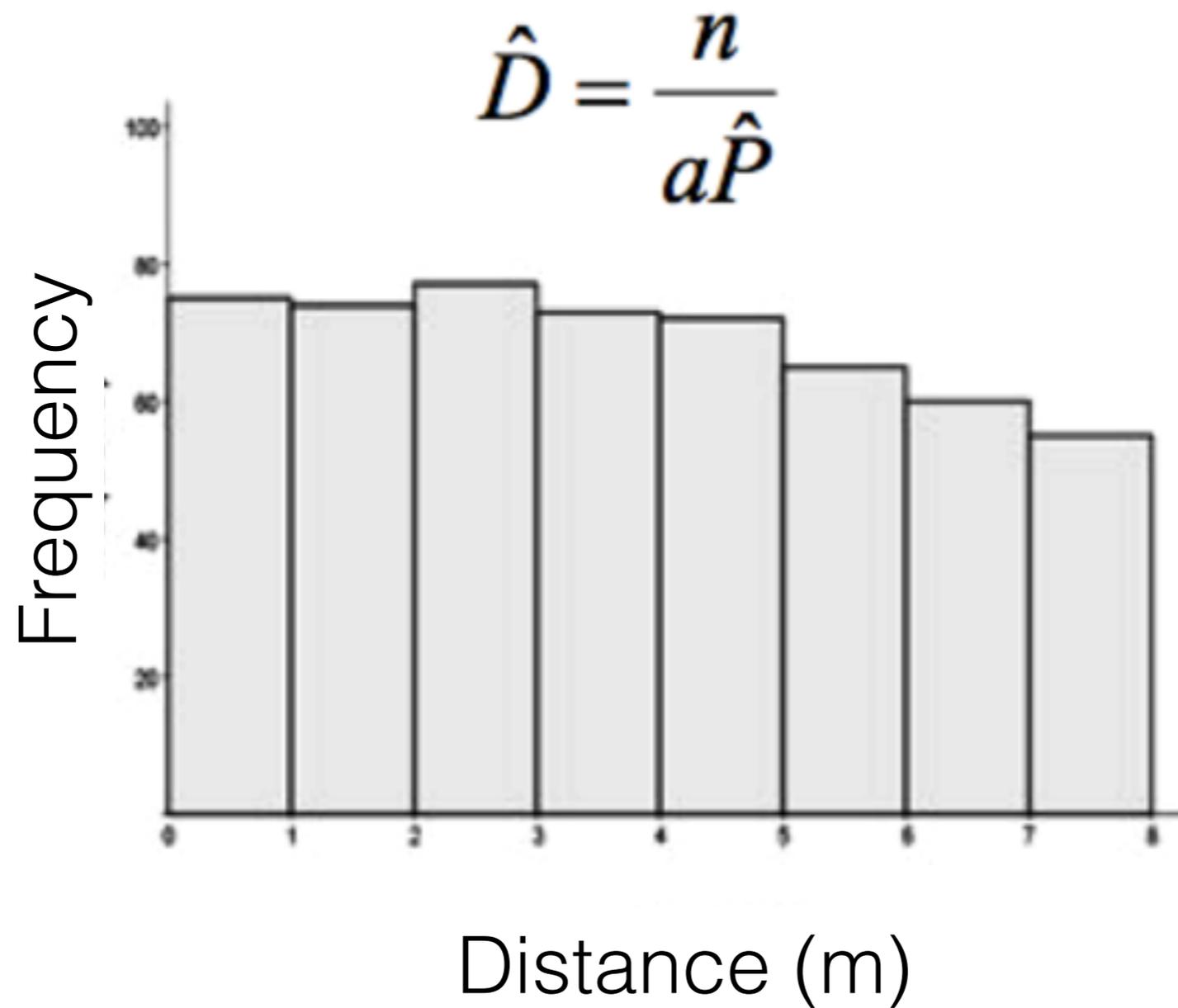
If we had perfect eyesight out to infinity...



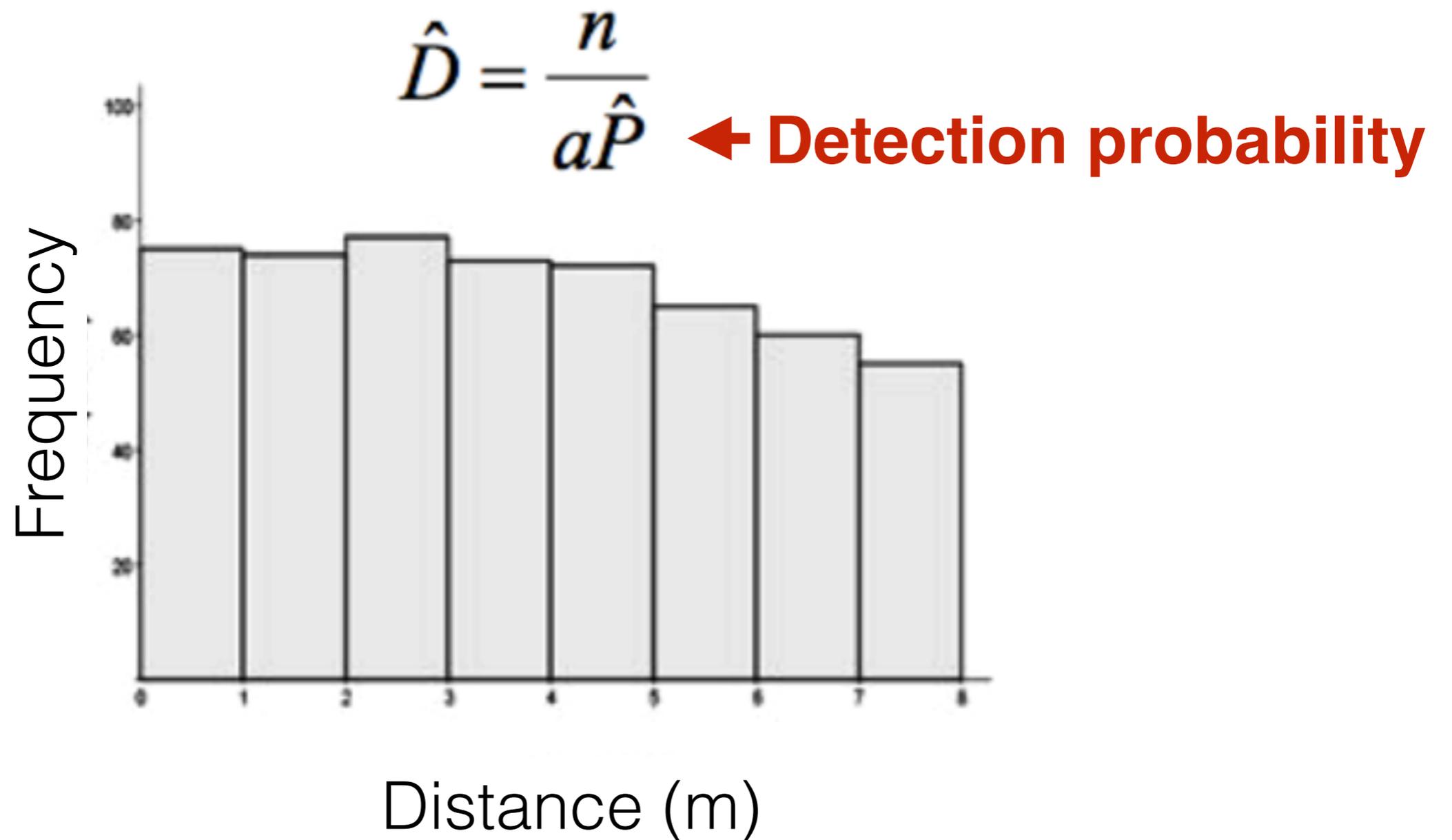
But we don't... detection declines with distance



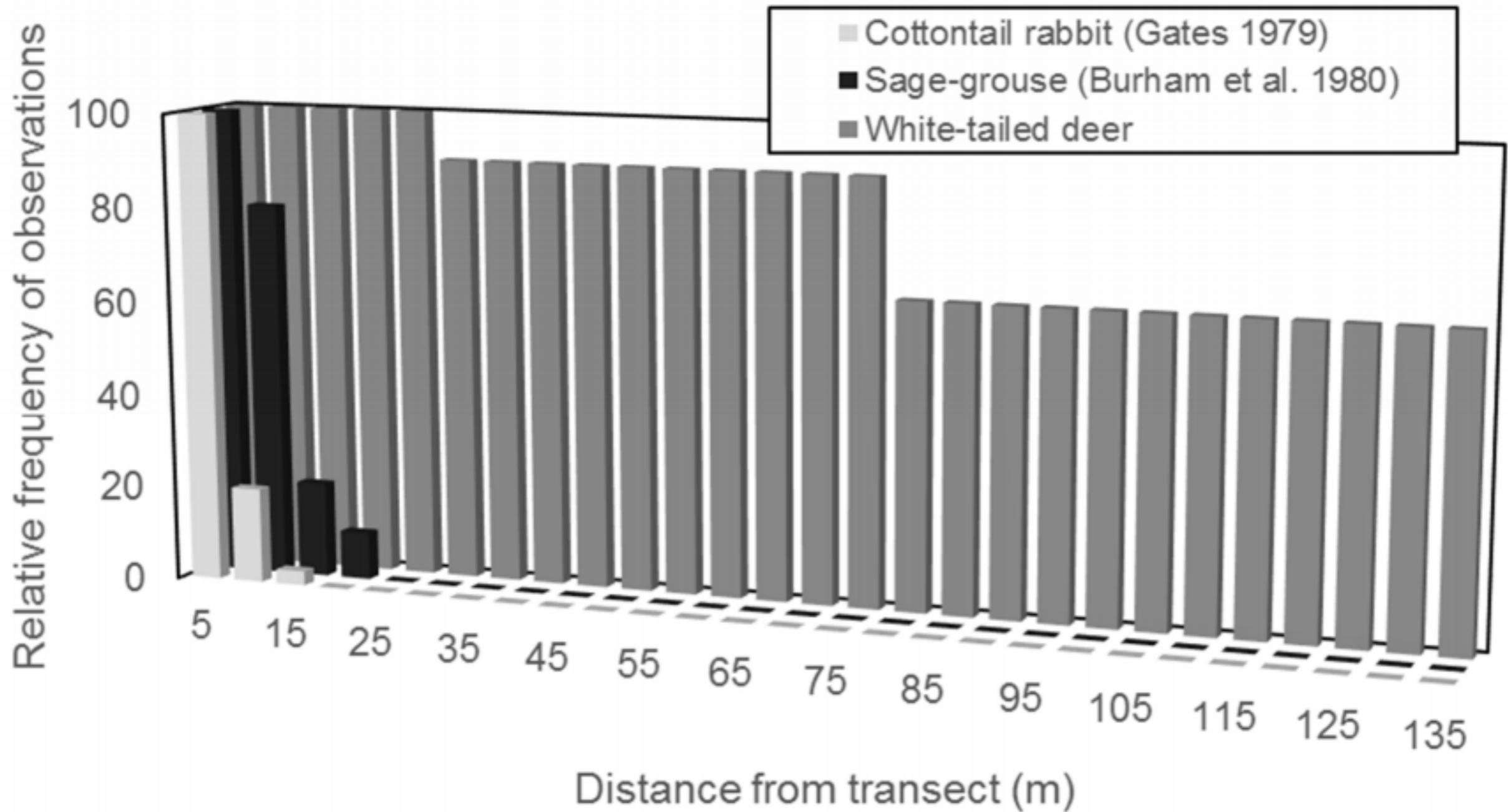
Which means we are missing some critters from our sampled area that were farther away



Which means we are missing some critters from our sampled area that were farther away



# Detection ~ distance relationship varies by species

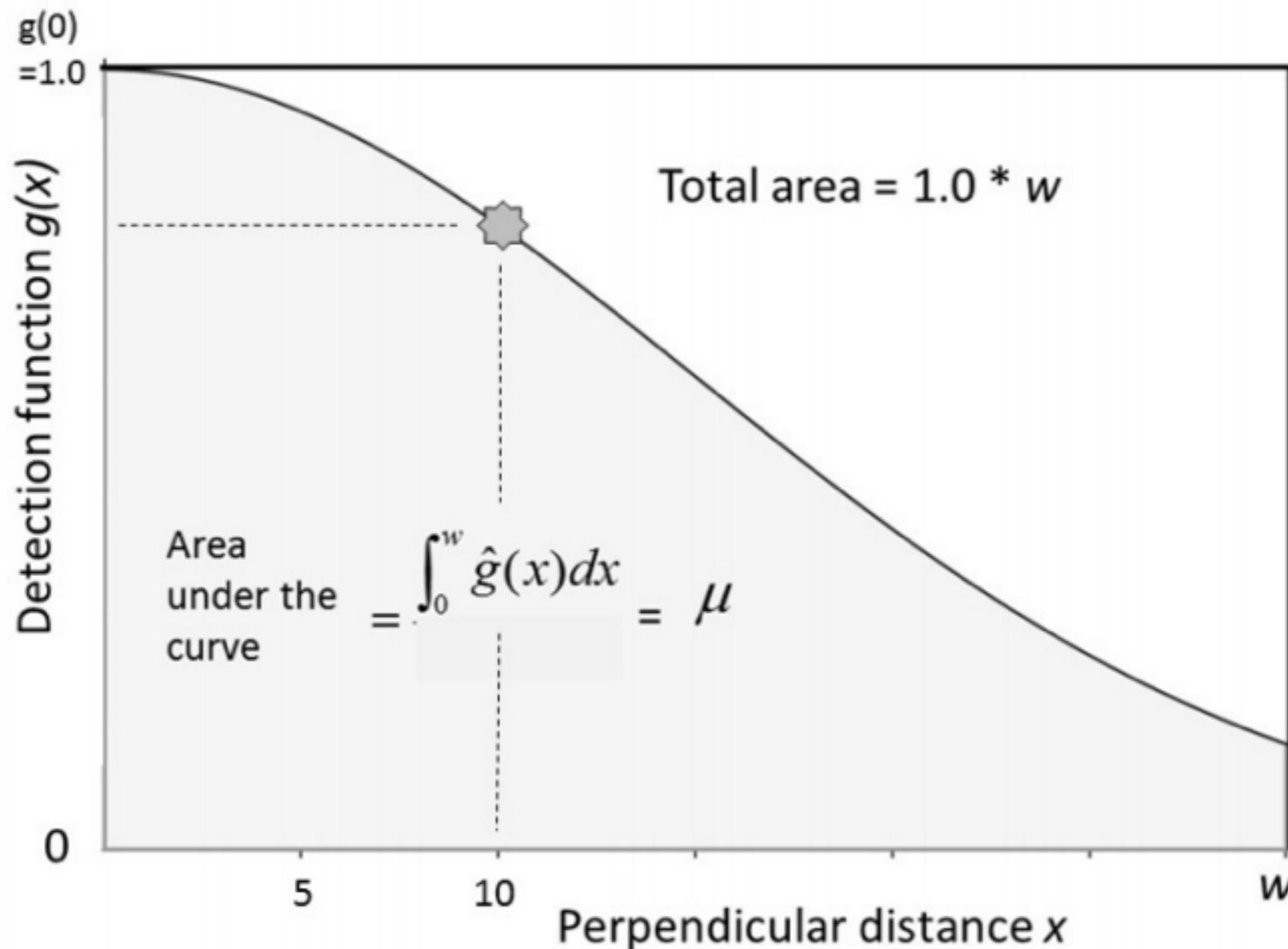


# Key assumptions of distance sampling:

- Transect lines (or points) are randomly placed
- Objects directly on/at the line/point are detected with certainty ( $P = 1.0$ )
- Objects are detected at their initial location
- Measurements or groupings of data are correct
- Sightings of individuals are independent events

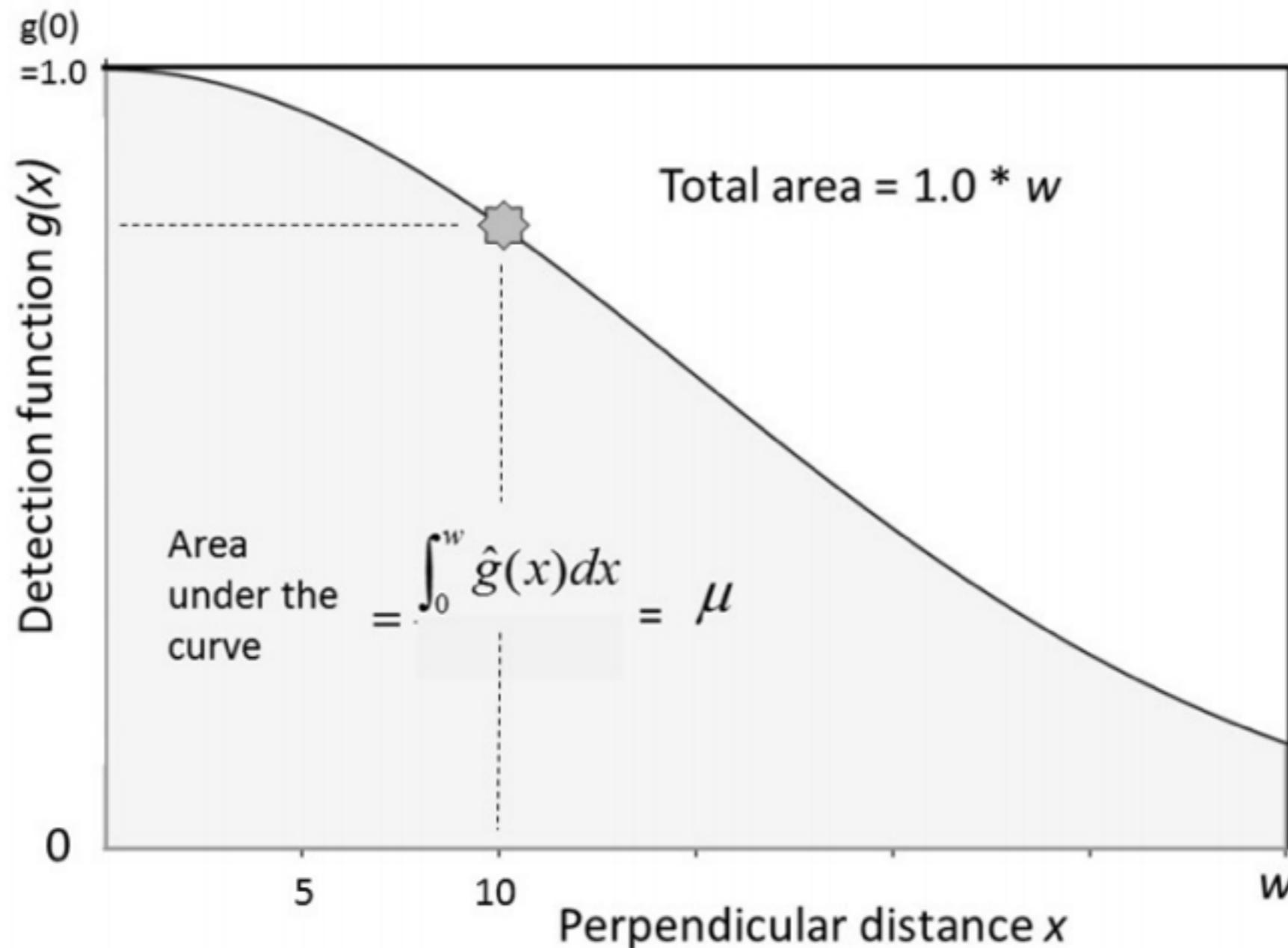
# A smooth detector function:

$P = \text{area under curve} / \text{total area}$



# A smooth detector function:

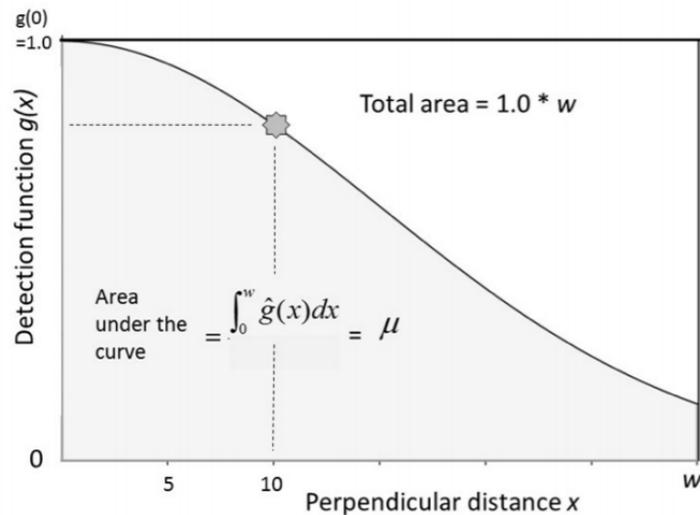
But we cannot observe probabilities of detection,  $g(x)$ , directly!  
What to do?



**truncation distance**



# A smooth detector function:

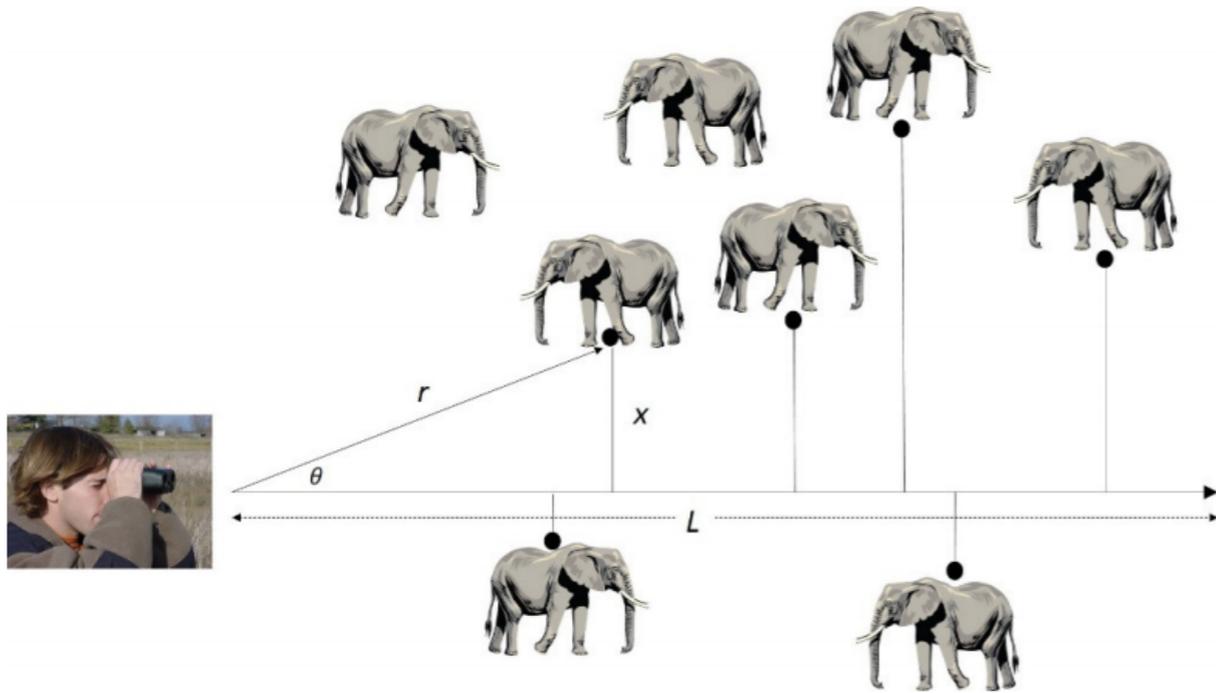


$f(x)$  we can quantify:  
the frequency of animals observed  
at different distances from observer

$f(x)$  is always  
scaled so max  
is 1



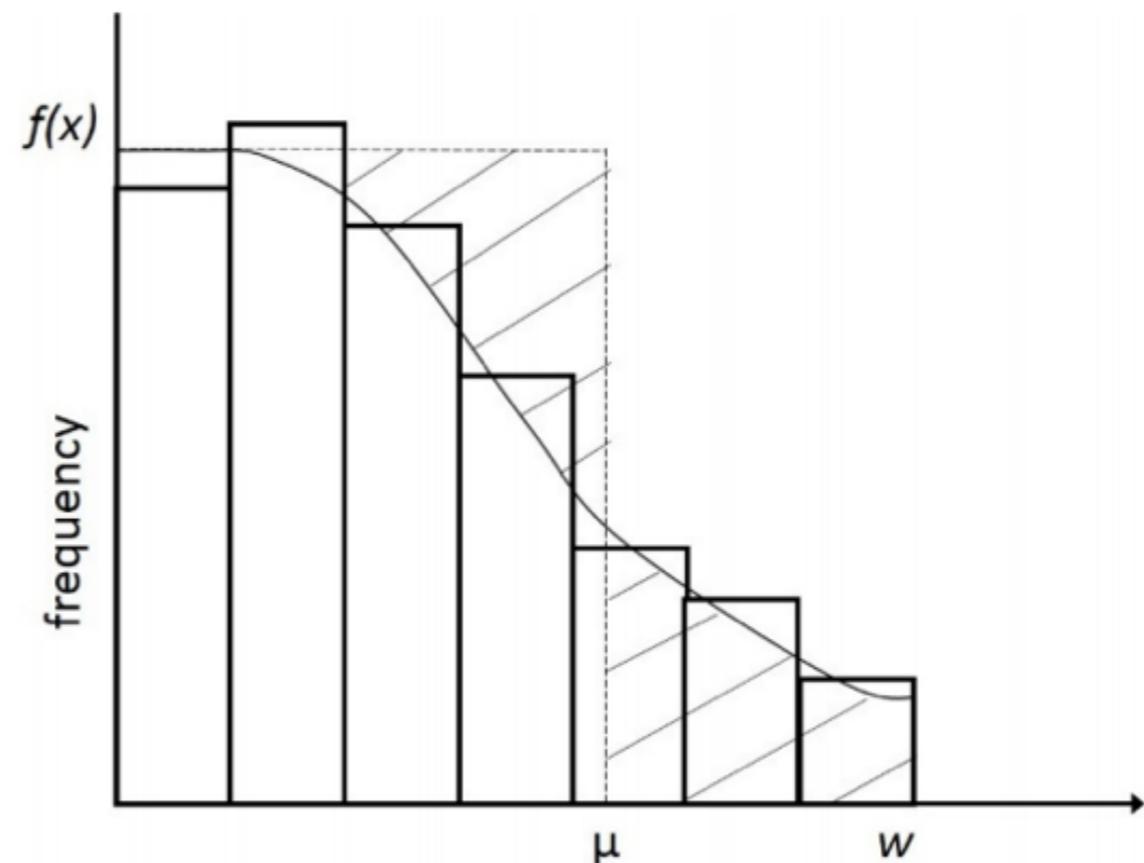
# $f(x)$ for line transect:



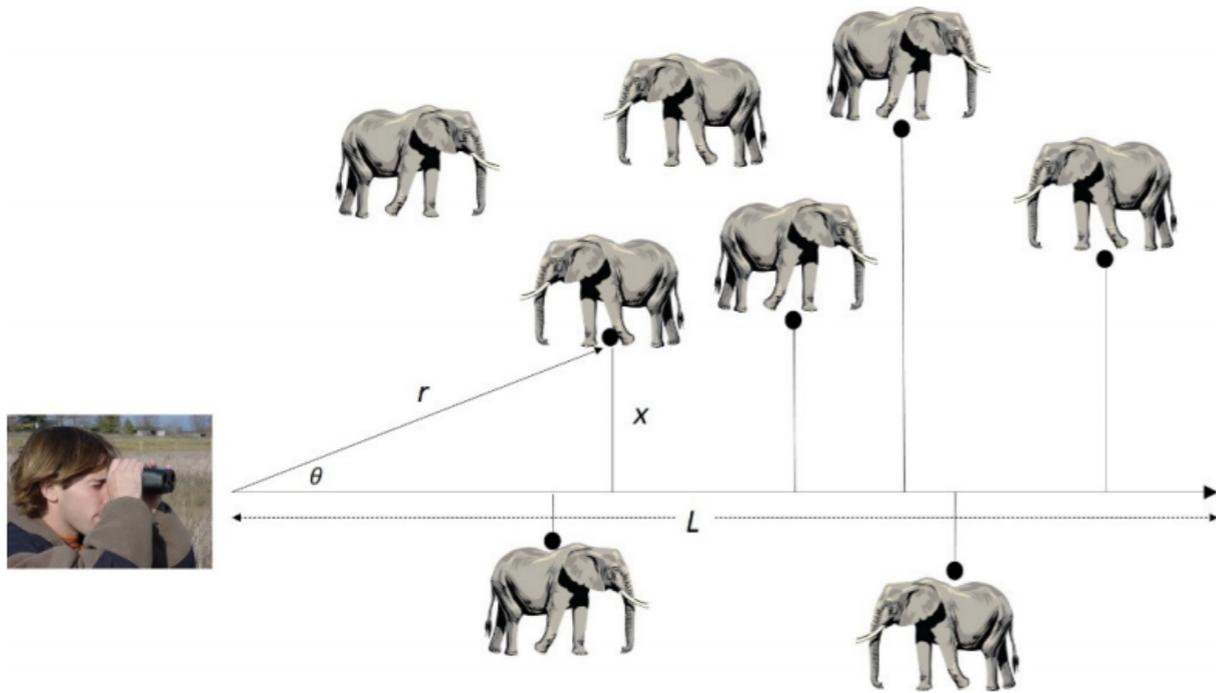
More animals detected closer to line than farther away

$$\hat{D} = \frac{n}{2w * L * K * \hat{P}}$$

↑  
**truncation distance**



# f(x) for line transect:

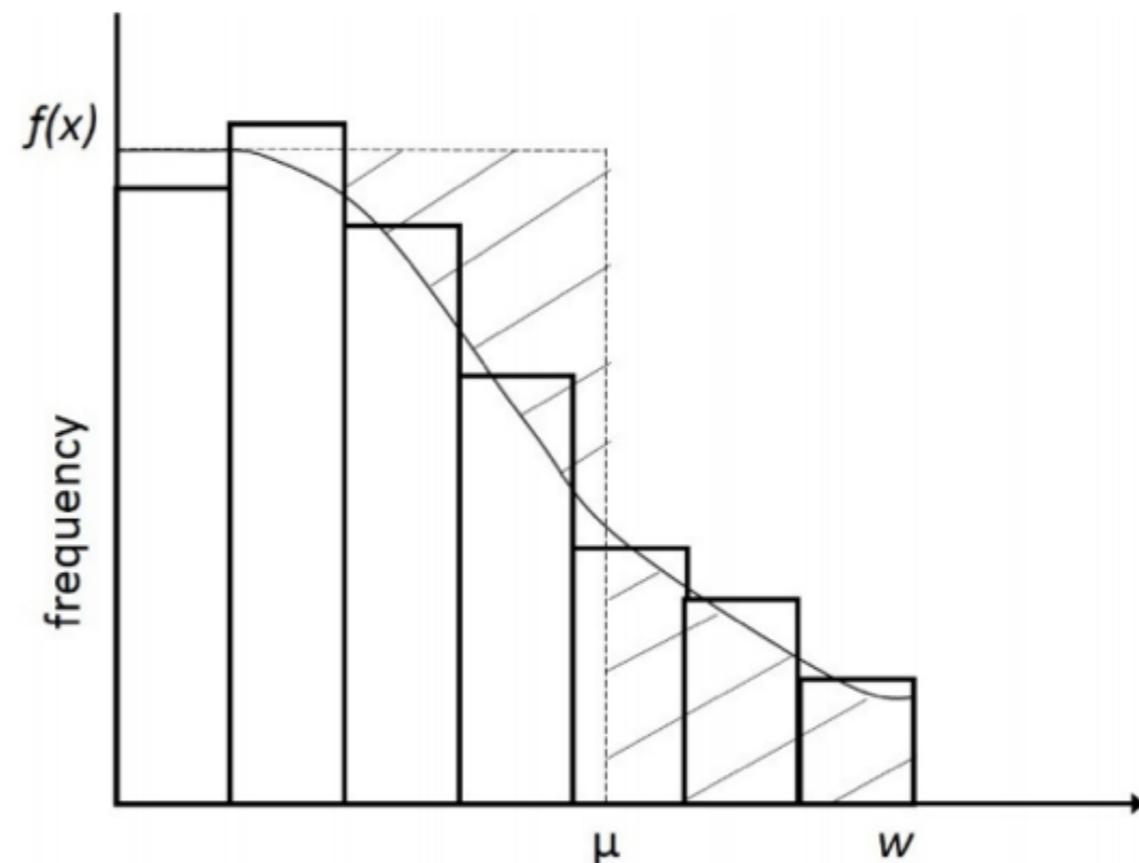


More animals detected closer to line than farther away

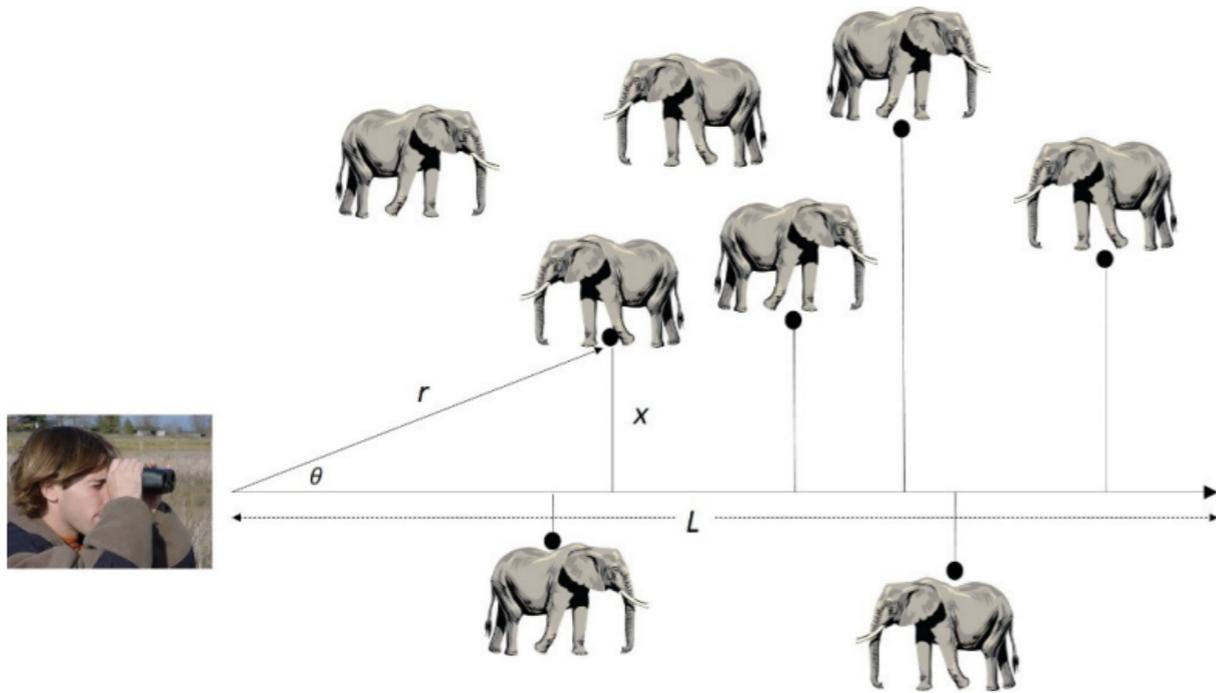
$$\hat{D} = \frac{n}{2w * L * K * \hat{P}}$$



**Length of transect**



# f(x) for line transect:

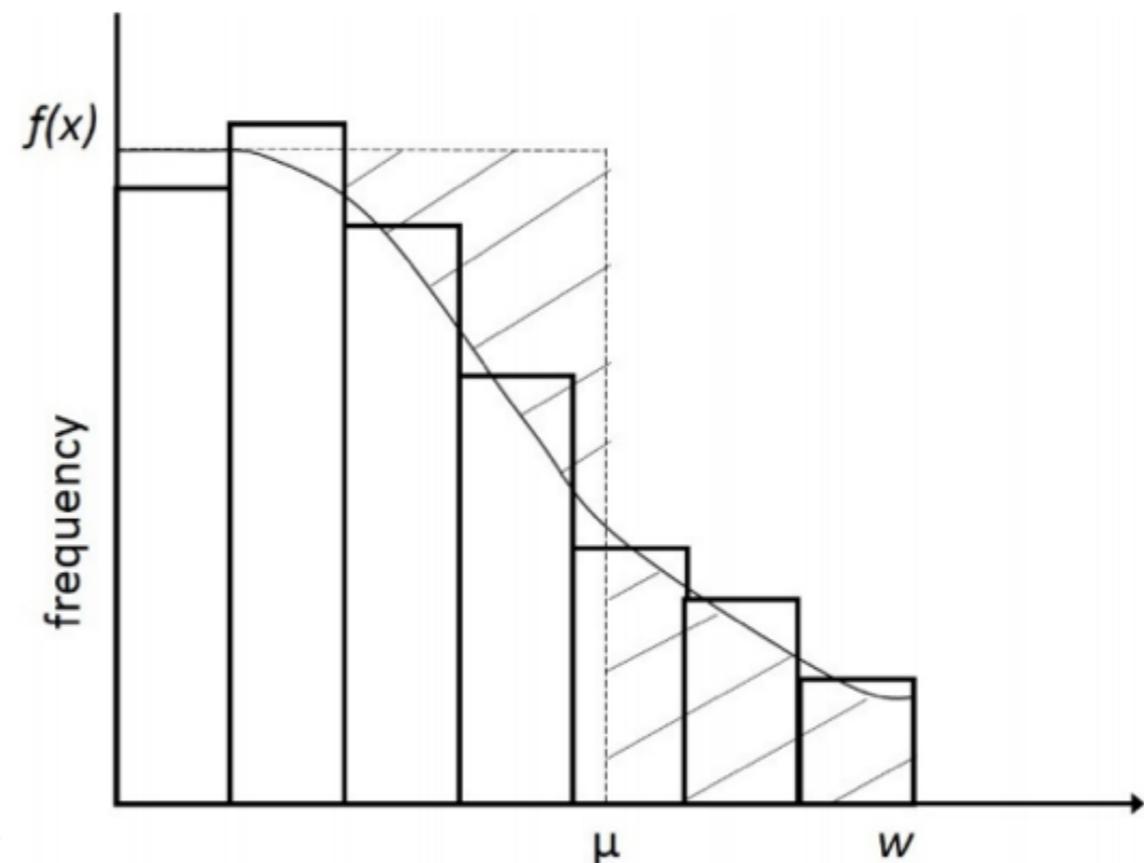


More animals detected closer to line than farther away

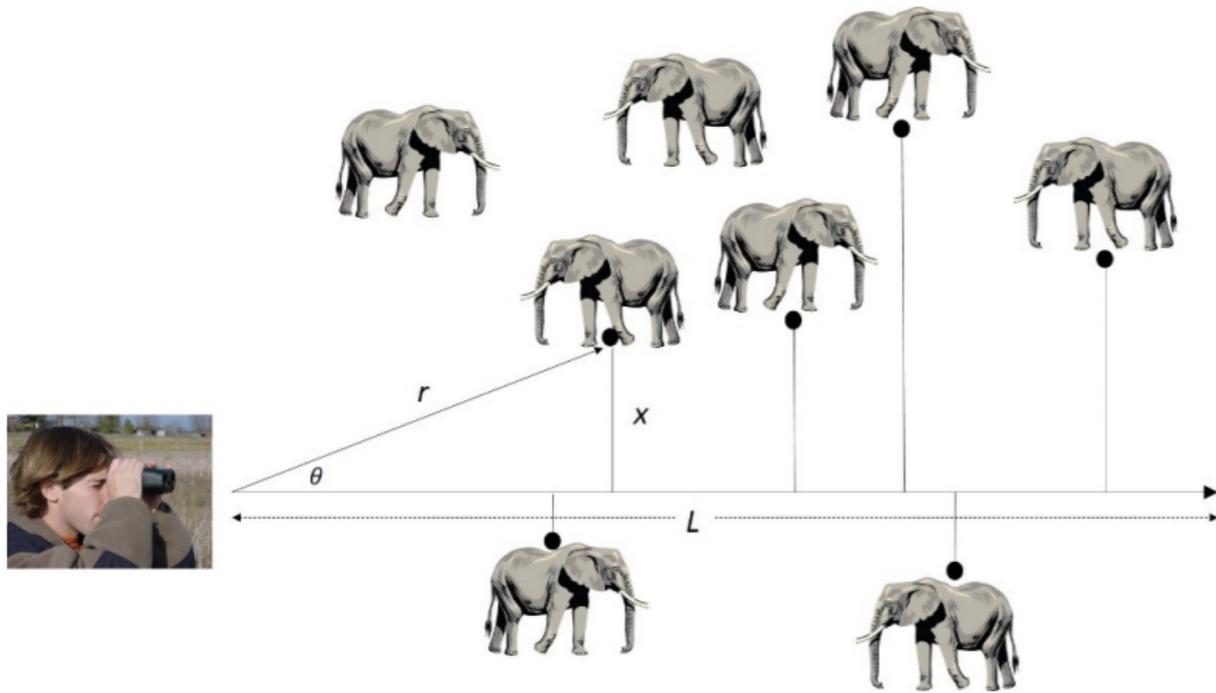
$$\hat{D} = \frac{n}{2w * L * K * \hat{P}}$$



**Total number of transects**



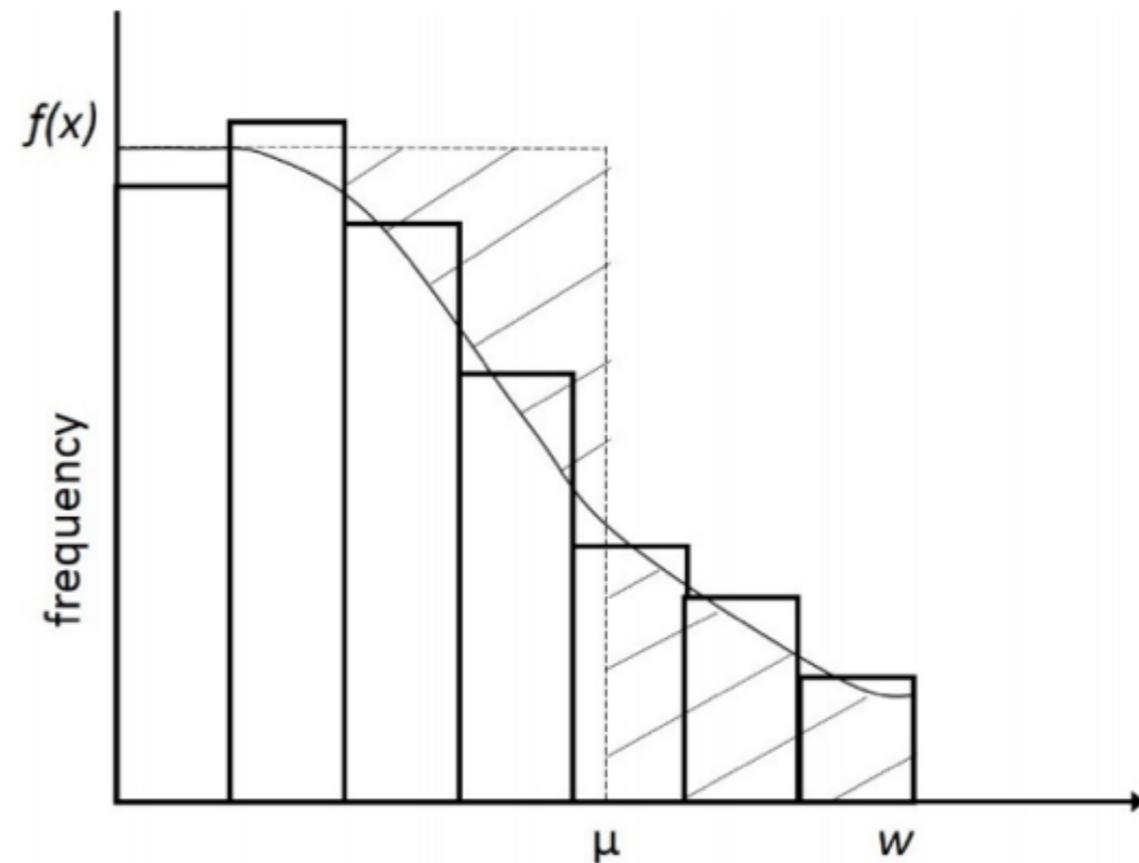
# f(x) for line transect:



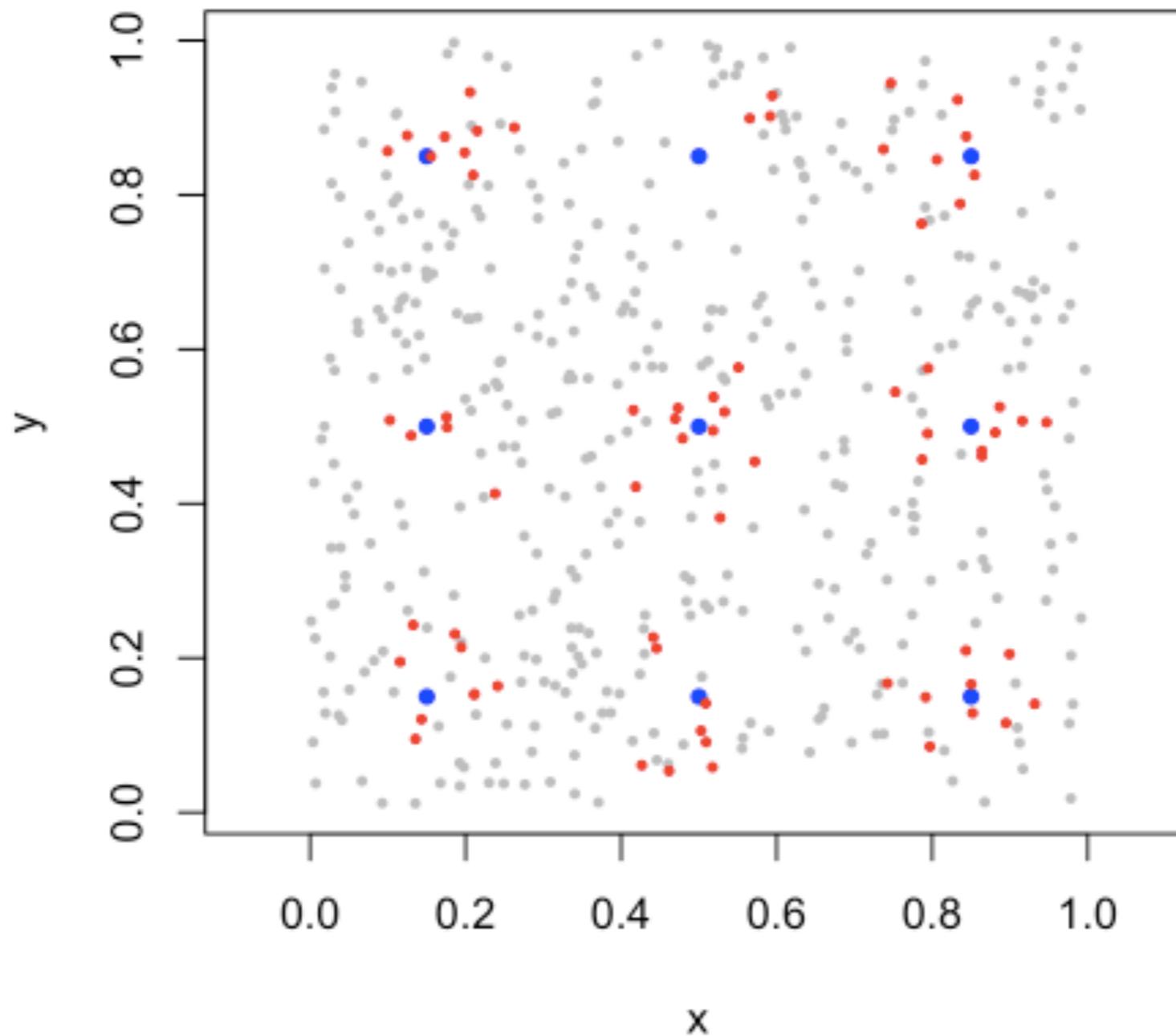
More animals detected closer to line than farther away

$$\hat{D} = \frac{n}{2w * \boxed{L * K} * \hat{P}}$$

↑  
**Effort**

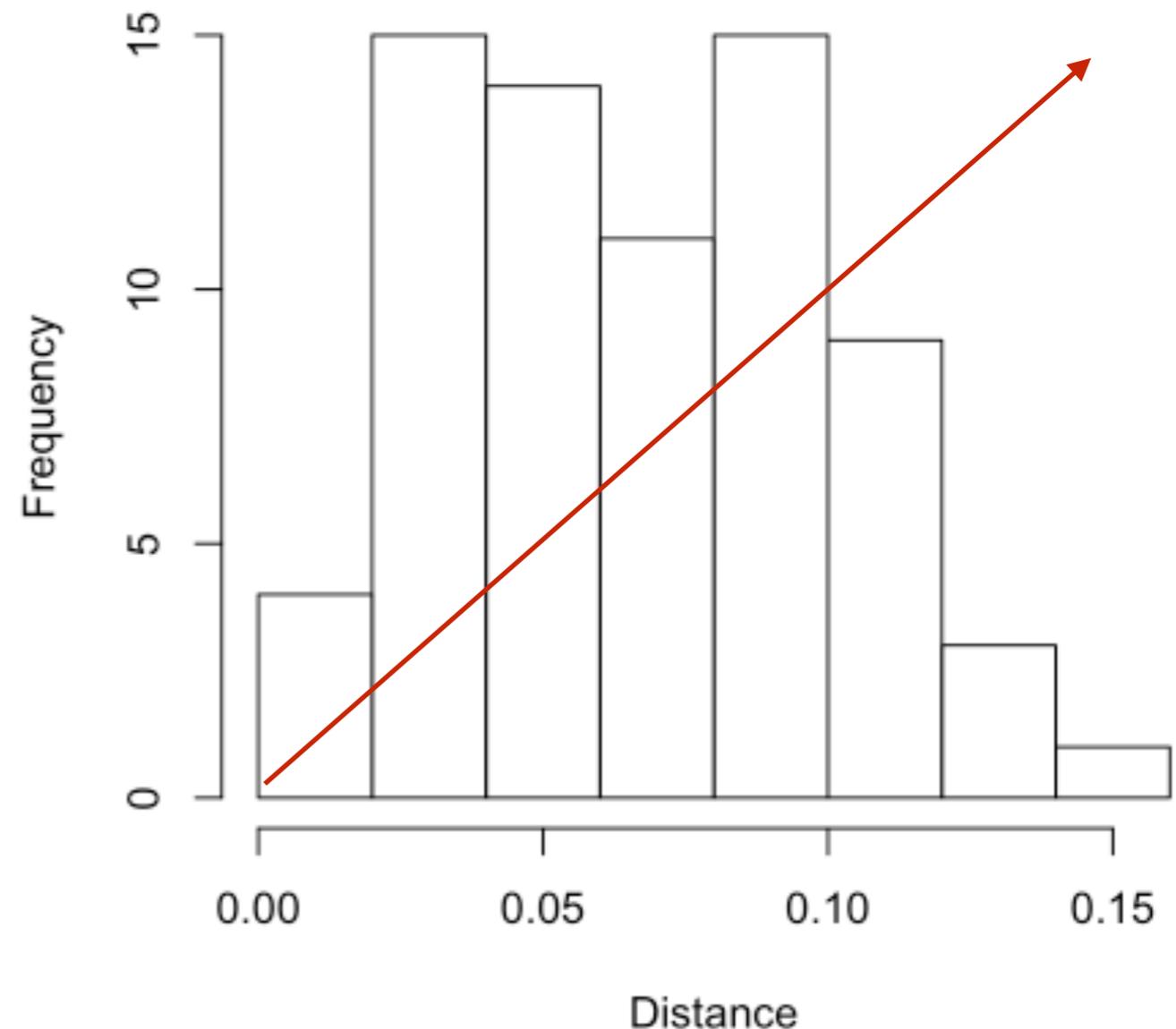
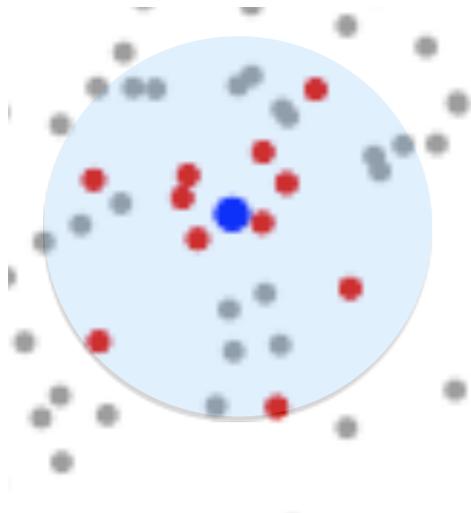


Could also count animals at points...



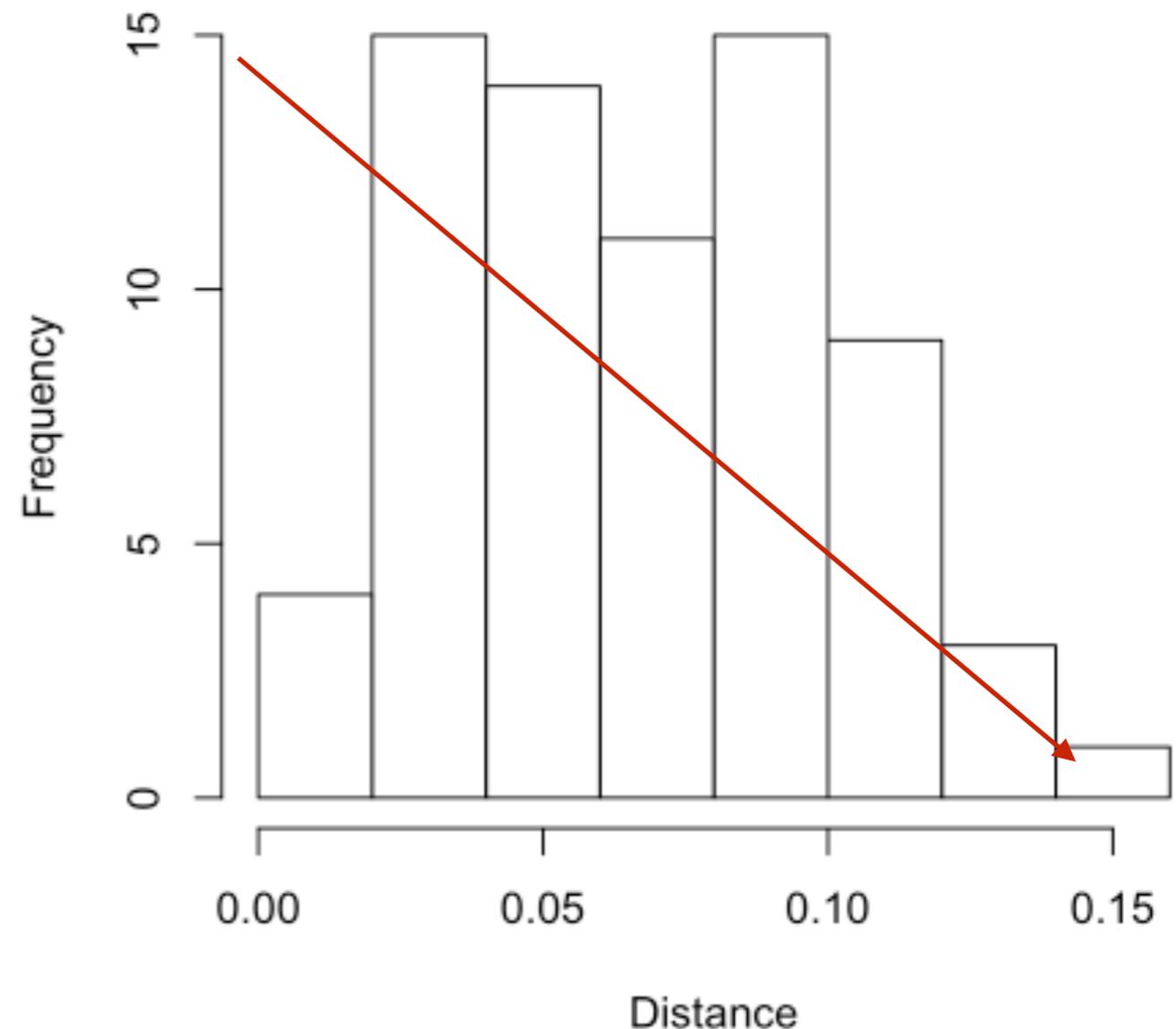
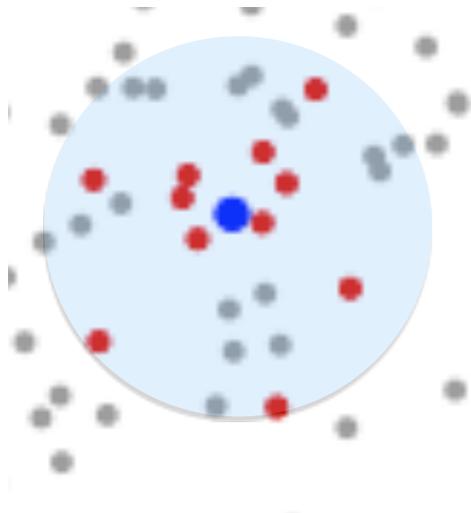
# Could also count animals at points...

- 1) As the radius increases, the area surveyed increases – so there are more animals available to be detected. This increases quadratically (since the area of the circle is  $\pi r^2$ ).

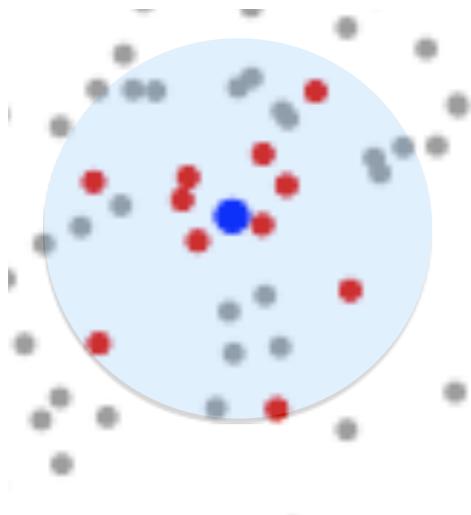


# Could also count animals at points...

- 2) At the same time, we are increasing the distance from the point to the animals in question, this is the same problem as described for line transects: as animals are further away, they are harder to detect.



Could also count animals at points...



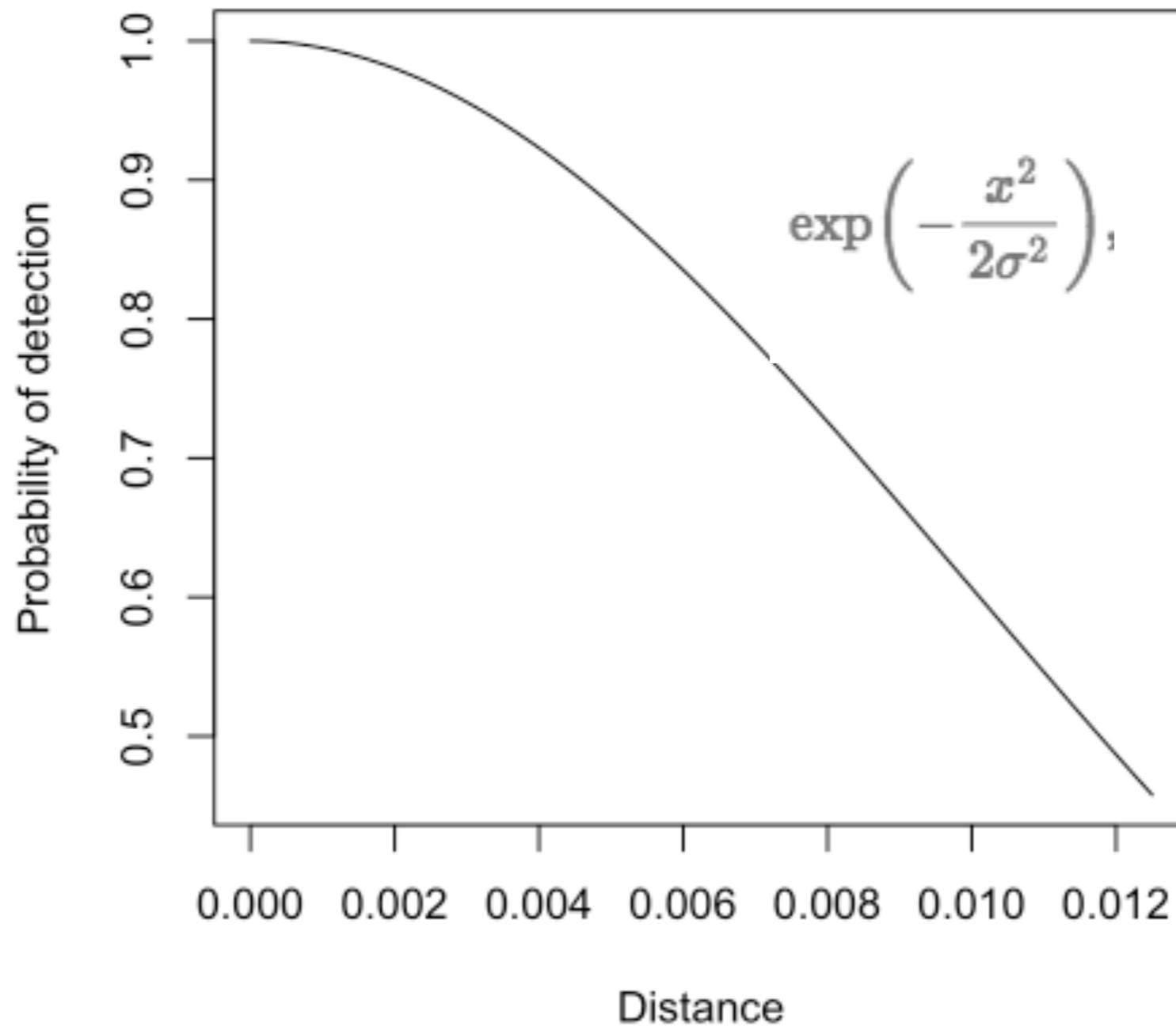
$$\hat{D} = \frac{n}{\pi \cdot w^2 \cdot K \cdot \hat{P}}$$



**# of points**

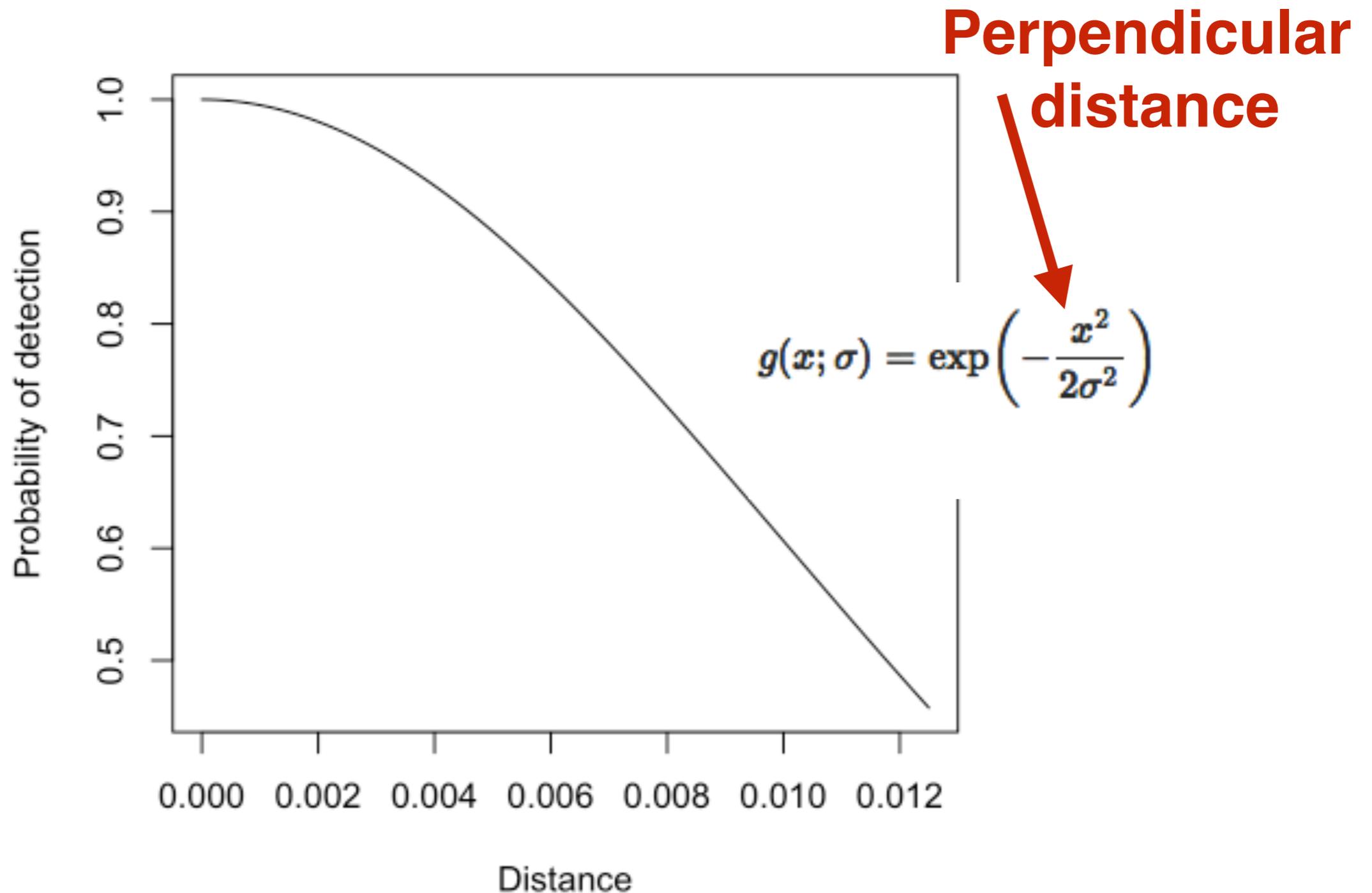
# Functions for detectability $\sim$ distance

The half-normal distribution



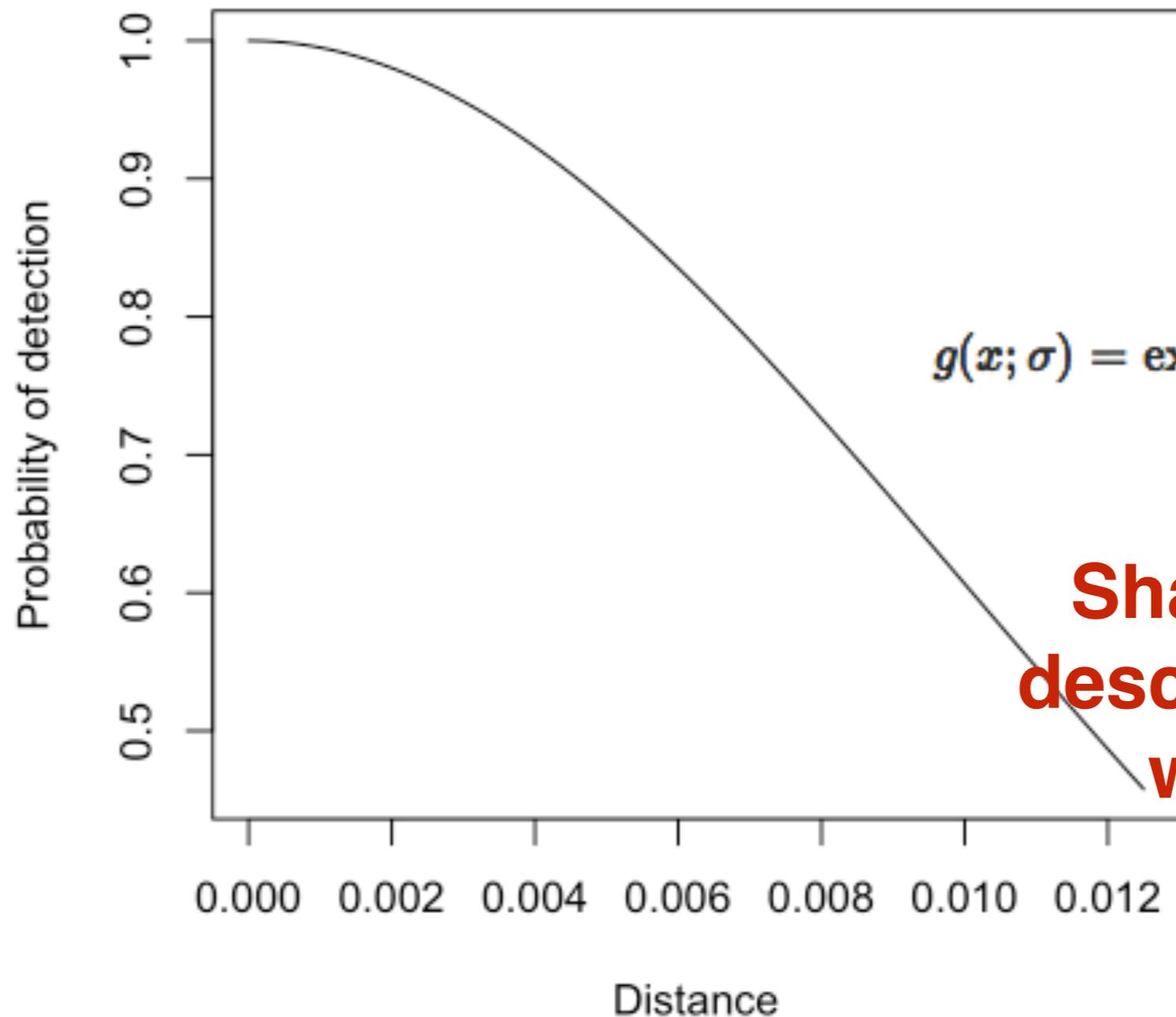
# Functions for detectability $\sim$ distance

The half-normal distribution



# Functions for detectability $\sim$ distance

The half-normal distribution

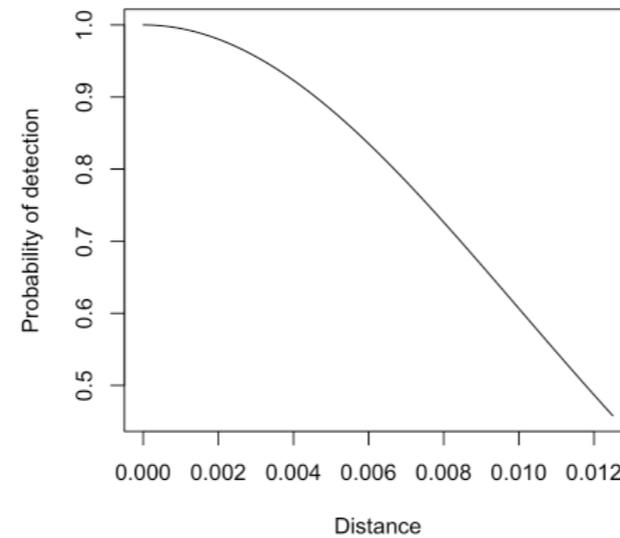


$$g(x; \sigma) = \exp\left(-\frac{x^2}{2\sigma^2}\right)$$

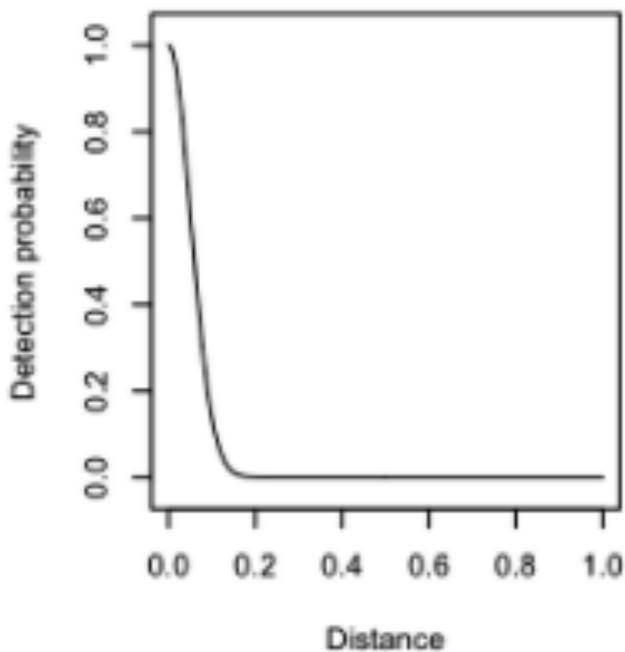
**Shape parameter,  
describes how likely  
we are to see  
an animal  
at a given  
distance**

# Functions for detectability $\sim$ distance

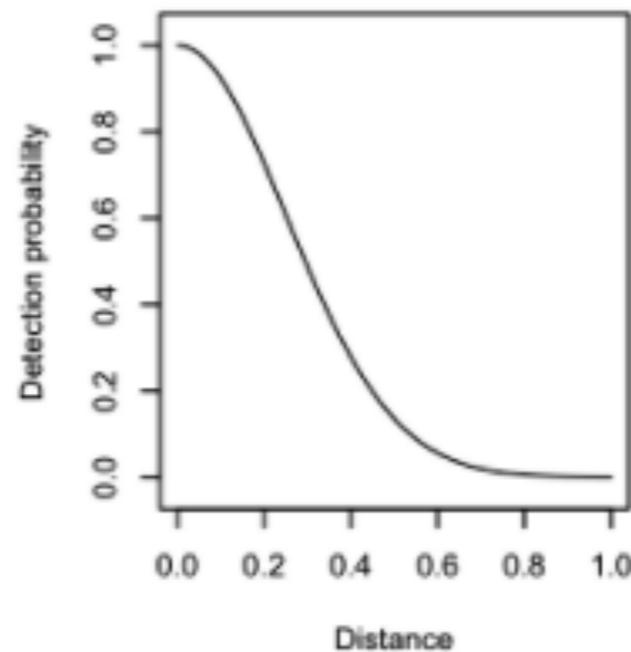
The half-normal distribution  $g(x; \sigma) = \exp\left(-\frac{x^2}{2\sigma^2}\right)$



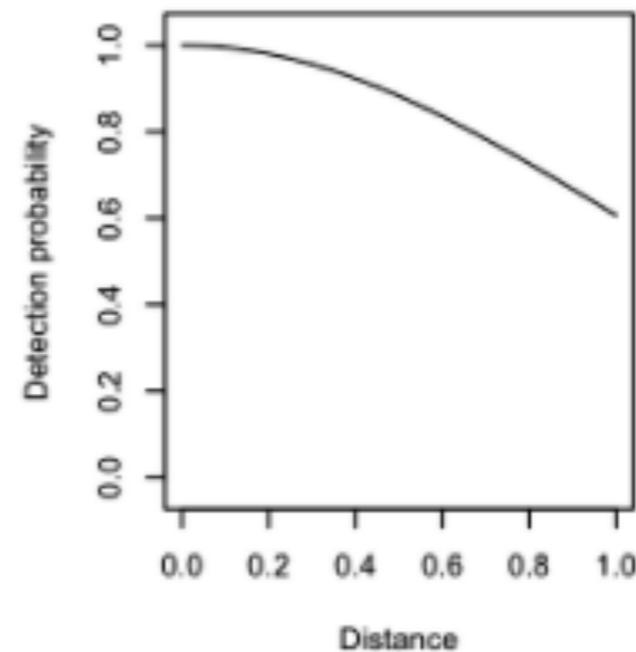
$\sigma = 0.05$



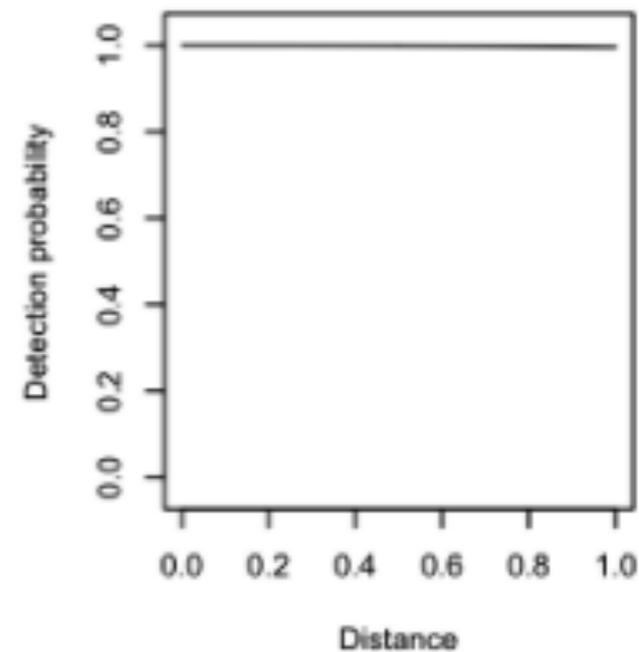
$\sigma = 0.25$



$\sigma = 1$

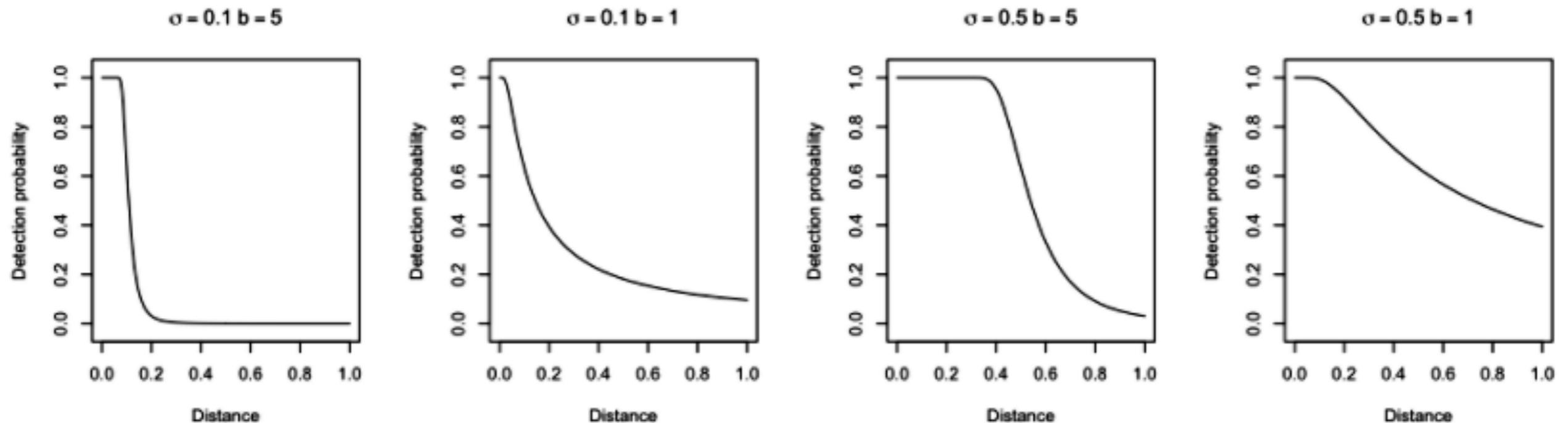


$\sigma = 10$



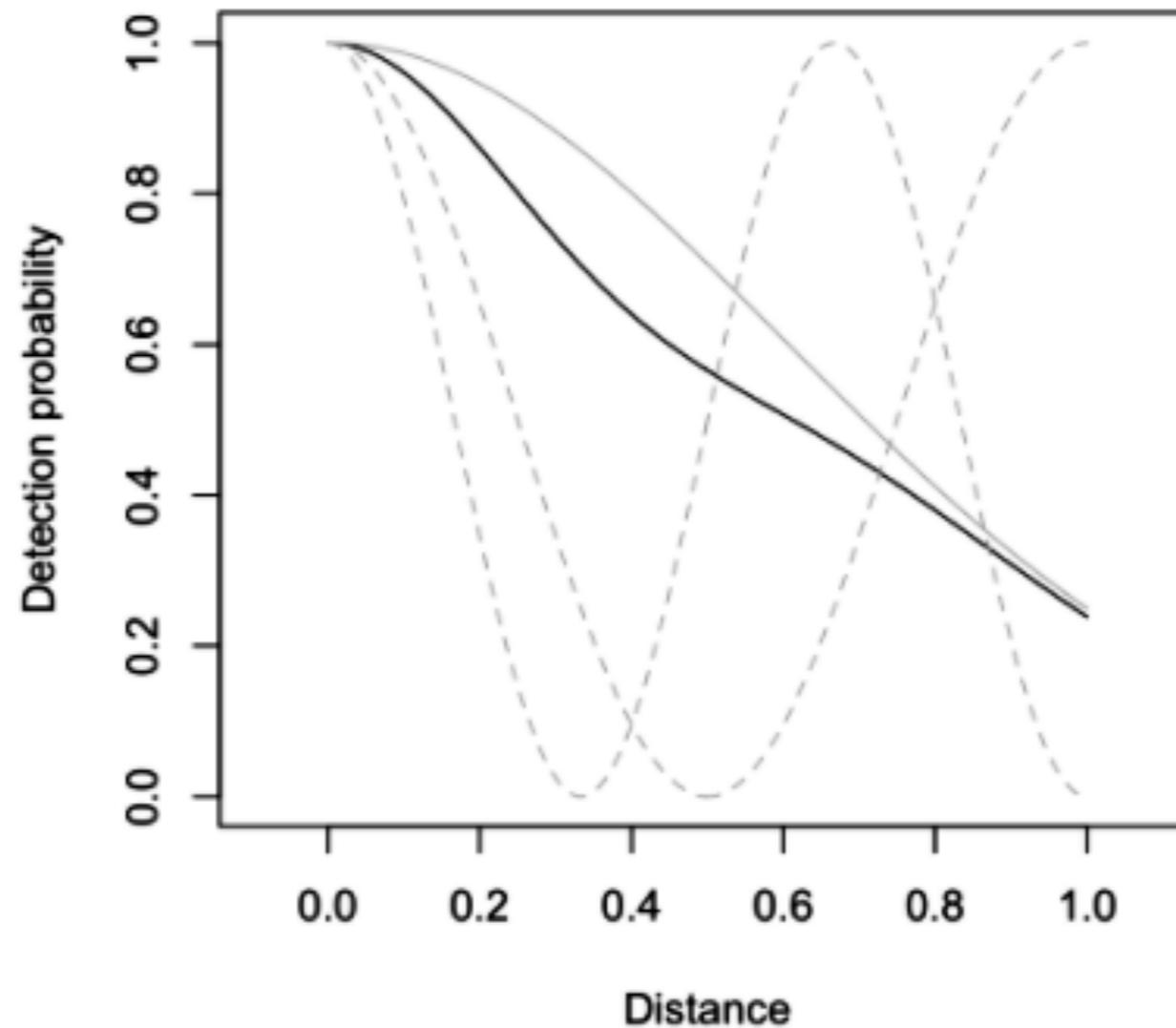
# Functions for detectability $\sim$ distance

The hazard distribution  $g(x; \sigma, b) = 1 - \exp\left(-\left(\frac{x}{\sigma}\right)^{-b}\right)$ .



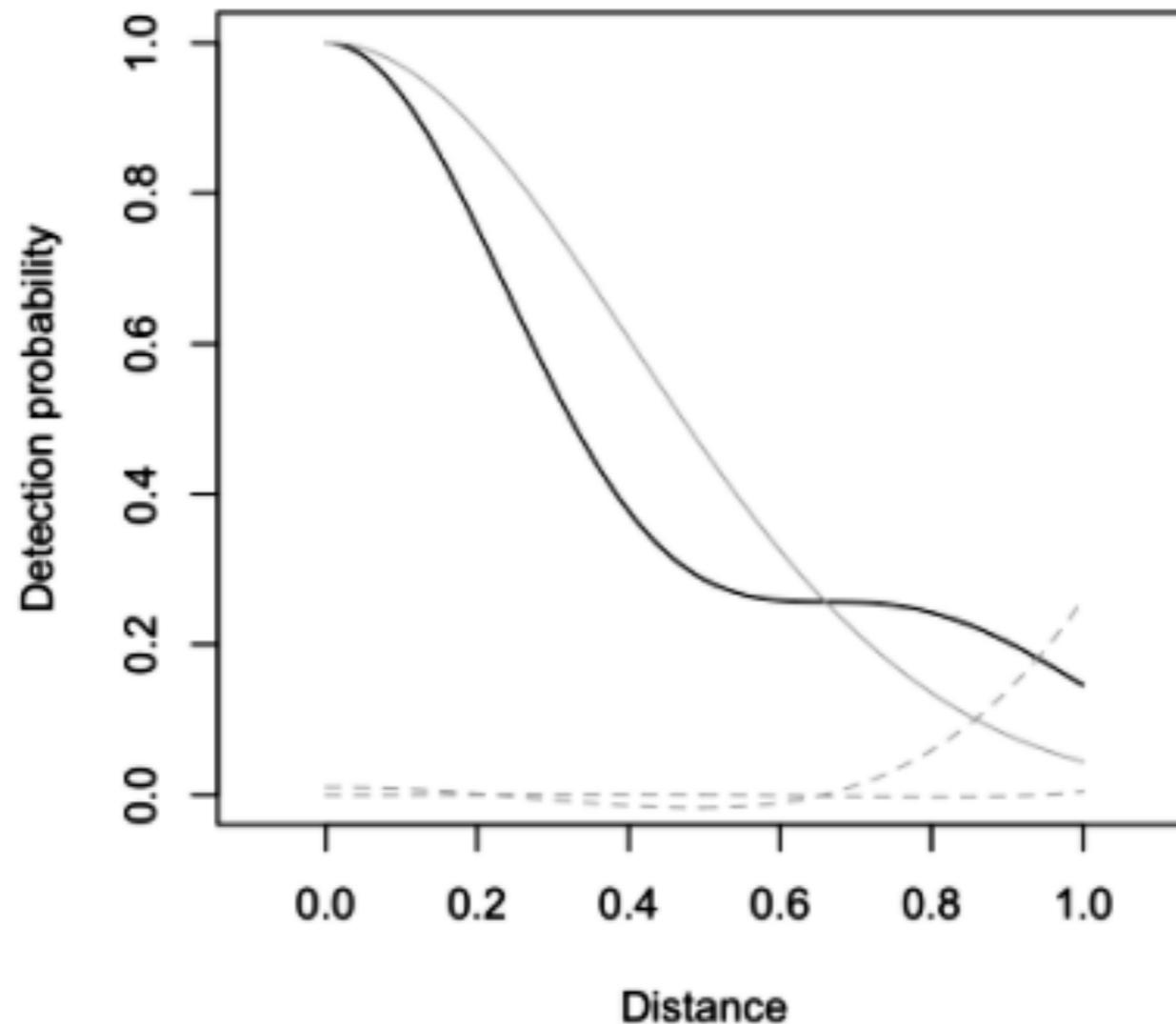
# Adjustments to detection functions: K + A

The cosine adjustment



# Adjustments to detection functions: K + A

Cosine adjustment allows for lots of shapes  
Also many other detection and adjustment functions



The simple polynomial adjustment

# What types of sampling does this cover?

- line transect sampling, in which the distances sampled are distances of detected objects (usually animals) from the line along which the observer travels
- point transect sampling, in which the distances sampled are distances of detected objects (usually birds) from the point at which the observer stands
- cue counting, in which the distances sampled are distances from a moving observer to each detected cue given by the objects of interest (usually whales)
- migration counts, in which the 'distances' sampled are actually times of detection during the migration of objects (usually whales) past a watch point

Tracey J. introduces Coon  
Creek data set

# Coding Challenge